

I. L. P. model : (p-median)

$$\text{Min } \sum_{i \in I} \sum_{j \in J} h_i \cdot d_{ij} \cdot y_{ij}$$

Subject to : $\sum_{j \in J} x_j = p$

$$\sum_{j \in J} y_{ij} = 1 \quad \forall i \in I$$

$$y_{ij} \leq x_j \quad \forall i \in I, j \in J$$

$$x_j \in \{0, 1\} \quad \forall j \in J$$

$$y_{ij} \in \{0, 1\} \quad \forall i \in I, j \in J$$

Obs 1 : (location and allocation) variables

as well as constraints are common to

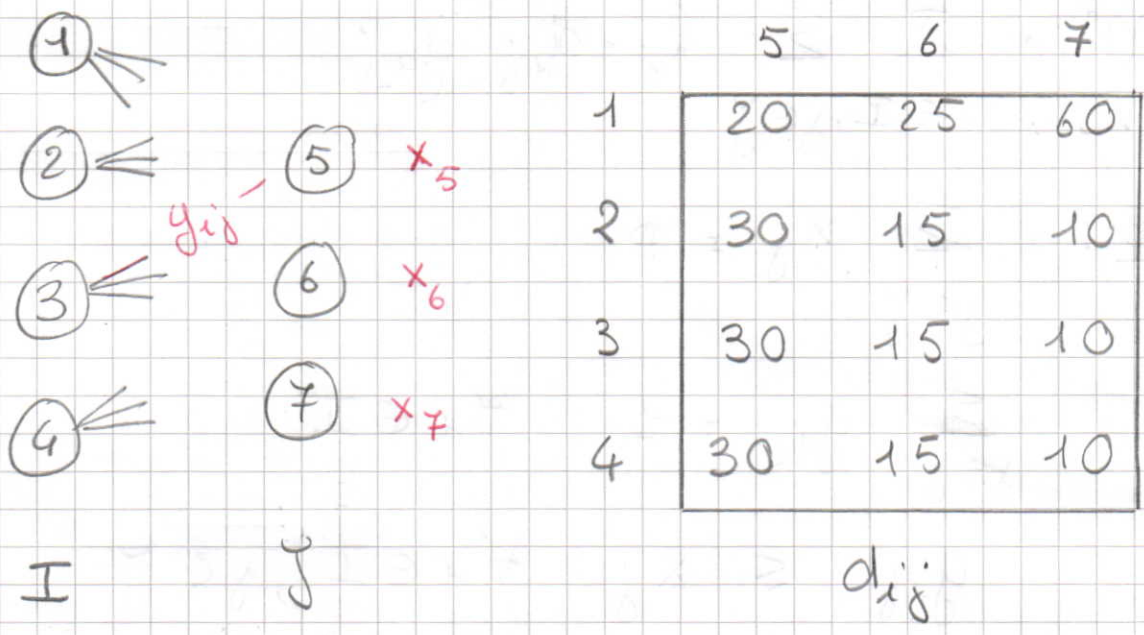
formulation (p-center) : only the objective function is different

Obs 2 : the formulation also minimizes the

average travel distance (just divide the objective function by $|I|$)

Time complexity : NP-Hard for variable values of p

Example (p-median)



< complete graph >

let $p=2$ and $h_i=1, i=1,2,3,4$

$$\begin{aligned} \text{Min } & 20 y_{15} + 25 y_{16} + 60 y_{17} + 30 y_{25} + \\ & + 15 y_{26} + 10 y_{27} + 30 y_{35} + 15 y_{36} + \\ & + 10 y_{37} + 30 y_{45} + 15 y_{46} + 10 y_{47} \end{aligned}$$

Sub. to: $x_5 + x_6 + x_7 = 2$

$$\left. \begin{aligned} y_{15} + y_{16} + y_{17} &= 1 \\ y_{25} + y_{26} + y_{27} &= 1 \\ \vdots \end{aligned} \right\} \begin{array}{l} \text{allocation} \\ \text{constraints} \end{array}$$

< the same for nodes 3 and 4 >

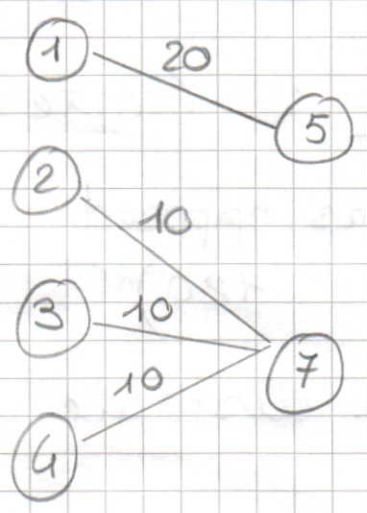
$$\begin{aligned}
 y_{15} &\leq x_5 \\
 y_{16} &\leq x_6 \\
 y_{17} &\leq x_7
 \end{aligned}
 \left. \vphantom{\begin{aligned} y_{15} \\ y_{16} \\ y_{17} \end{aligned}} \right\} \text{linking between location and allocation}$$

< the same for the other links >

$$x_5, x_6, x_7 \in \{0, 1\}$$

$$y_{15}, y_{16}, y_{17}, \dots \in \{0, 1\}$$

What is an optimal solution of the toy example? by inspection:



$$x_5^* = x_7^* = 1 \quad x_6^* = 0$$

$$y_{15}^* = y_{25}^* = y_{37}^* = y_{47}^* = 1$$

($y_{ij}^* = 0$ other.)

with optimal value \equiv
minimum total distance = 50

Observe that this solution is also optimal for the p-center problem defined on the same instance: the minimum maximum distance is 20!