

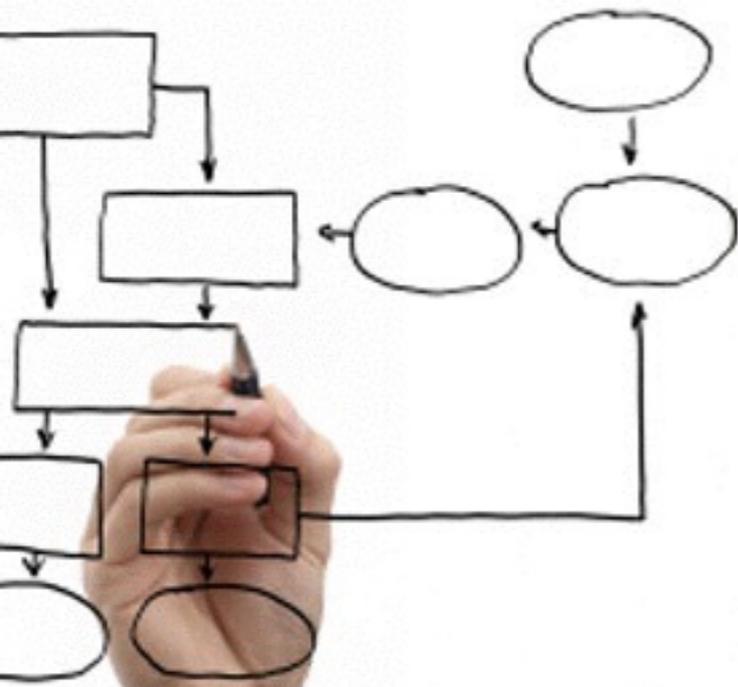
# Methods for the specification and verification of business processes

MPB (6 cfu, 295AA)

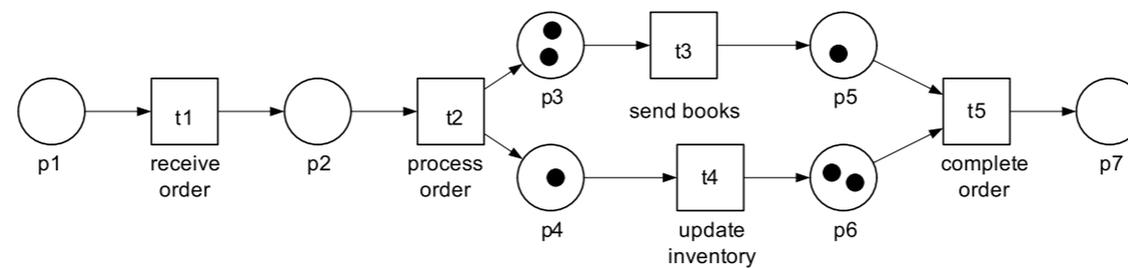
Roberto Bruni

<http://www.di.unipi.it/~bruni>

07 - Introduction to nets



# Object



M. Weske: Business Process Management,  
© Springer-Verlag Berlin Heidelberg 2007

## Overview of the basic concepts of Petri nets

Free Choice Nets (book, optional reading)

<https://www7.in.tum.de/~esparza/bookfc.html>

# Why Petri nets

Business process analysis:

**validation:** testing correctness

**verification:** proving correctness

**performance:** planning and optimization

Use of Petri nets (or alike)

visual + formal

tool supported

# Approaching Petri nets

Are you familiar with automata / transition systems?  
They are fine for sequential protocols / systems  
but do not capture concurrent behaviour directly

A Petri net is a mathematical model  
of a parallel and concurrent system

in the same way that a finite automaton is a  
mathematical model of a sequential system

# Approaching Petri nets

Petri net theory can be studied  
at several level of details

We study some basics aspects, relevant to the  
analysis of business processes

Petri nets have a faithful and convenient graphical  
representation, that we introduce and motivate next

# Finite automata examples

# Applications

Finite automata are widely used, e.g., in  
protocol analysis,  
text parsing,  
video game character behavior,  
security analysis,  
CPU control units,  
natural language processing,  
speech recognition,  
mechanical devices  
(like elevators, vending machines, traffic lights)  
and many more ...

# How to

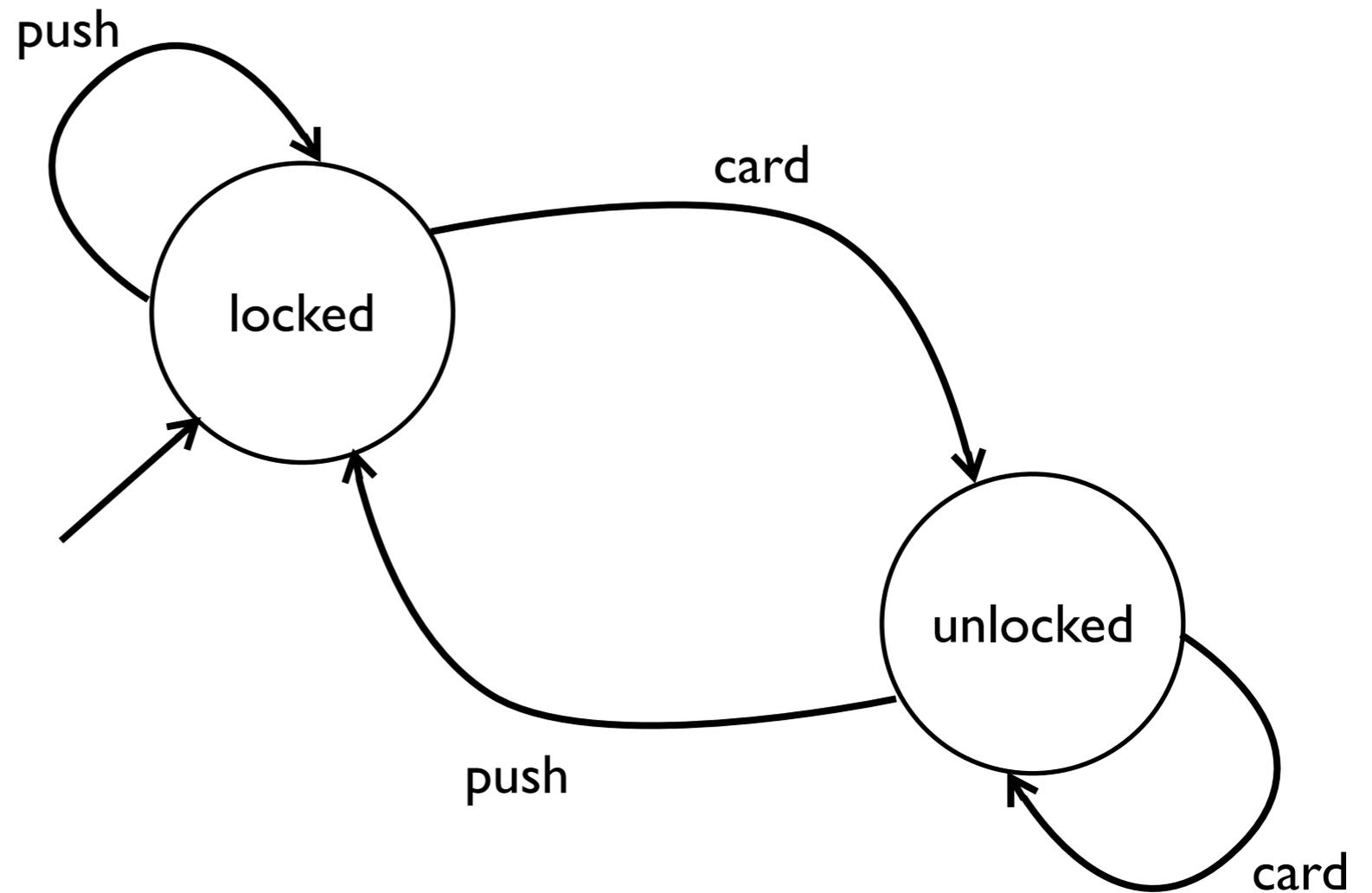
Identify the admissible states of the system  
Optional: Mark some states as error states

Add transitions  
to move from one state to another  
(no transition to recover from error states)

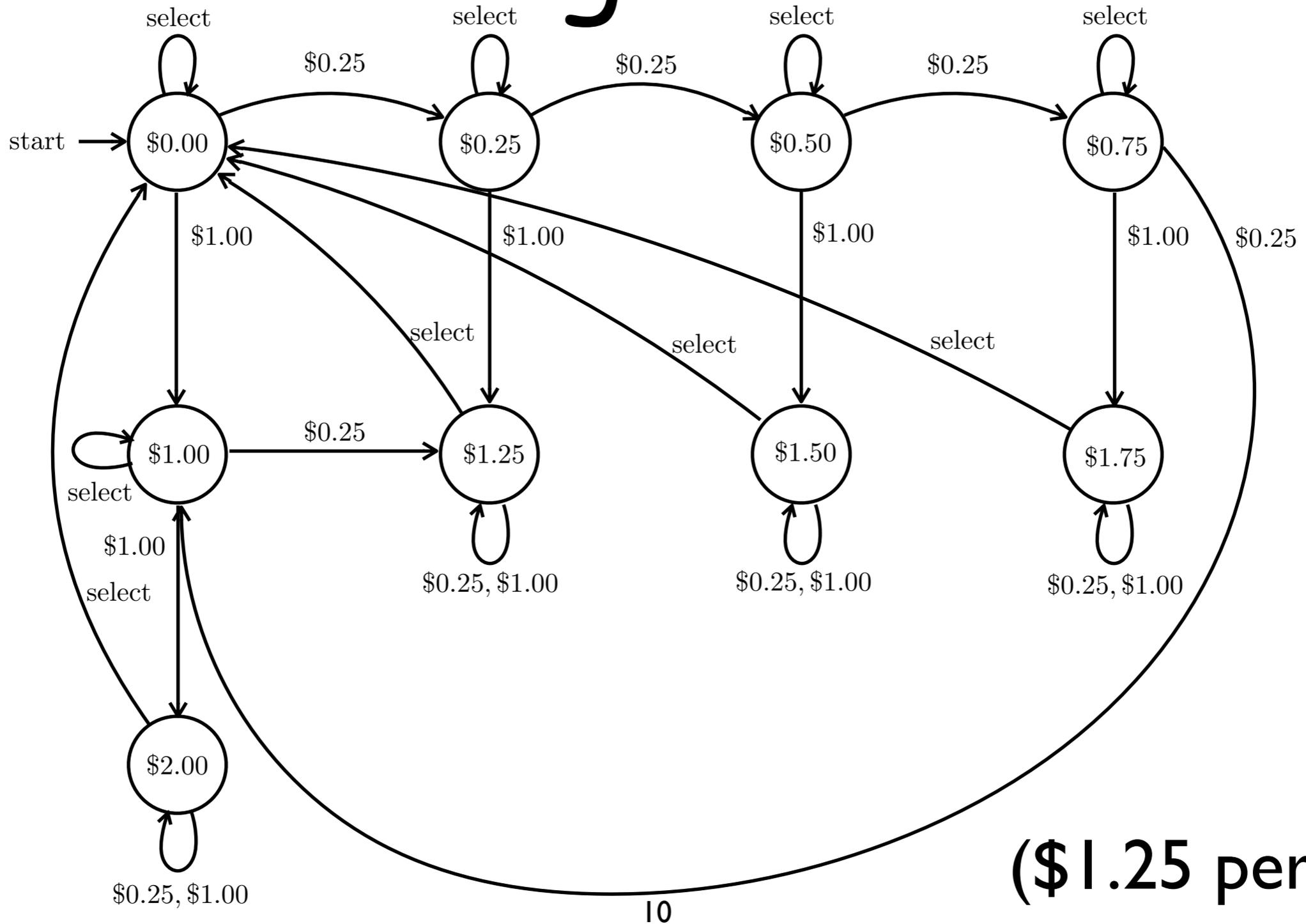
Set the starting state

Optional: Mark some states as final

# Example: Turnstile



# Example: Vending Machine

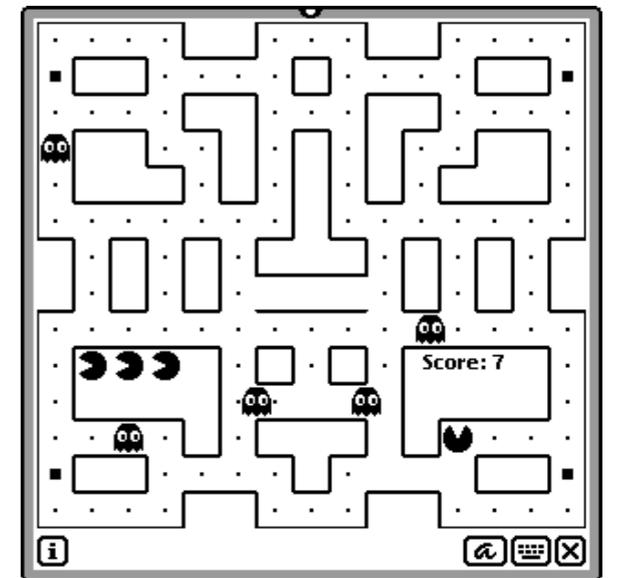


# Computer controlled characters for games

States = characters behaviours

Transitions = labelled by events that cause a change  
in behaviour

Example:  
Pac-man moves in a maze  
wants to eat pills  
is chased by ghosts



by eating power pills, pac-man can defeat ghosts

# Example: Pac-Man Ghosts



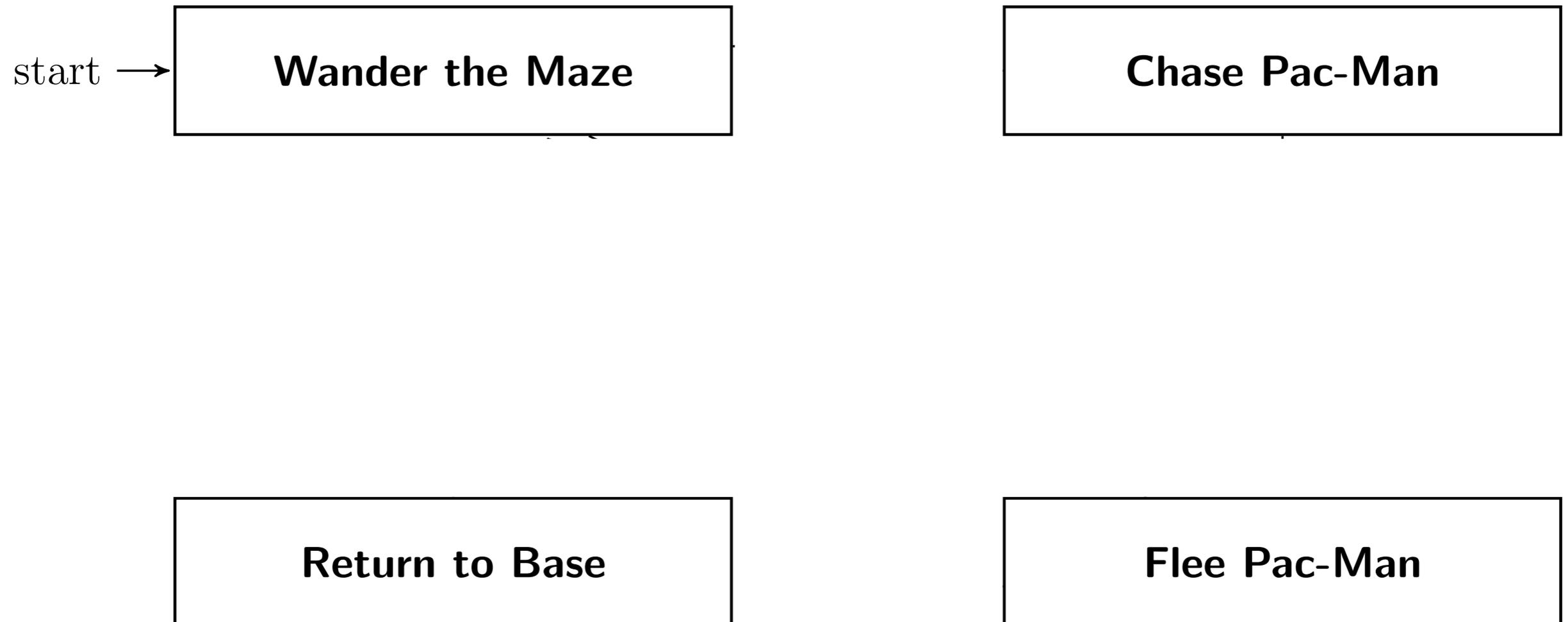
**Wander the Maze**

**Chase Pac-Man**

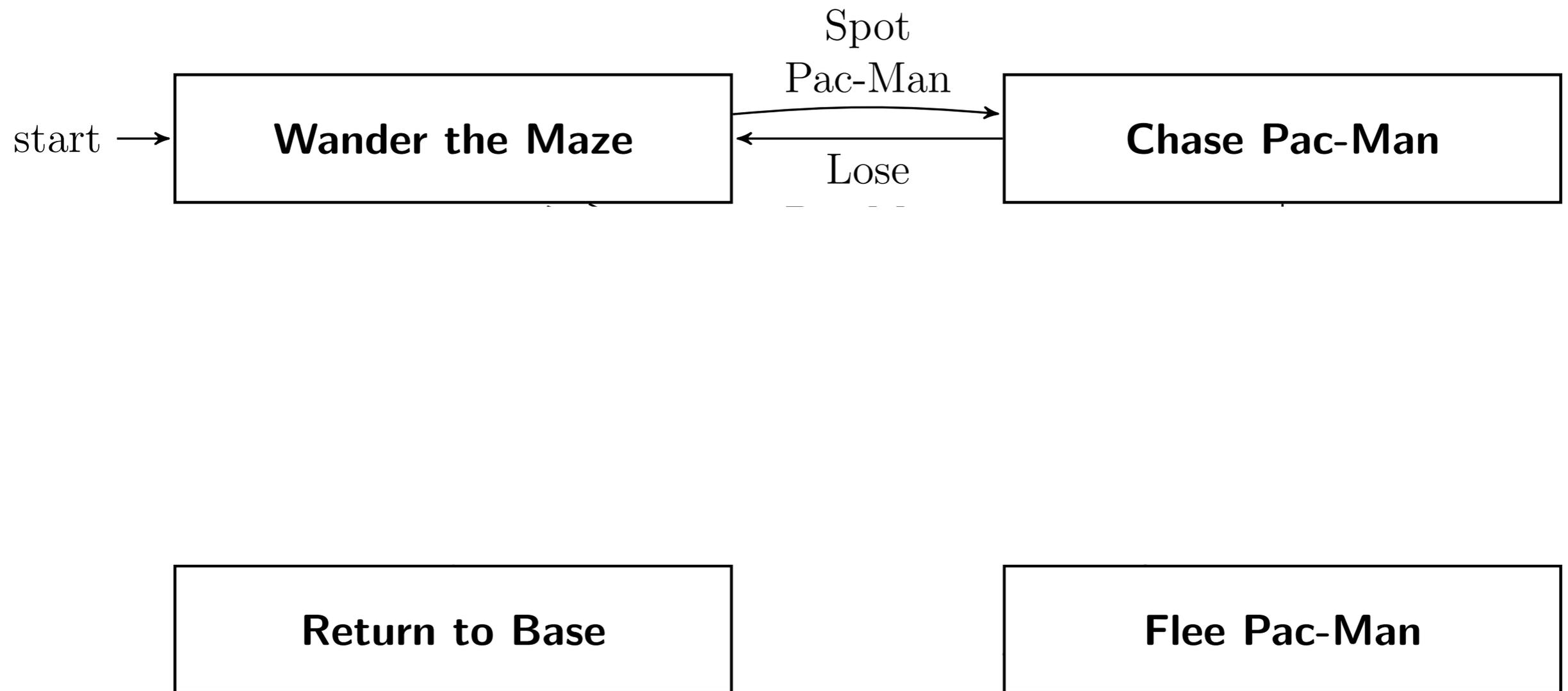
**Return to Base**

**Flee Pac-Man**

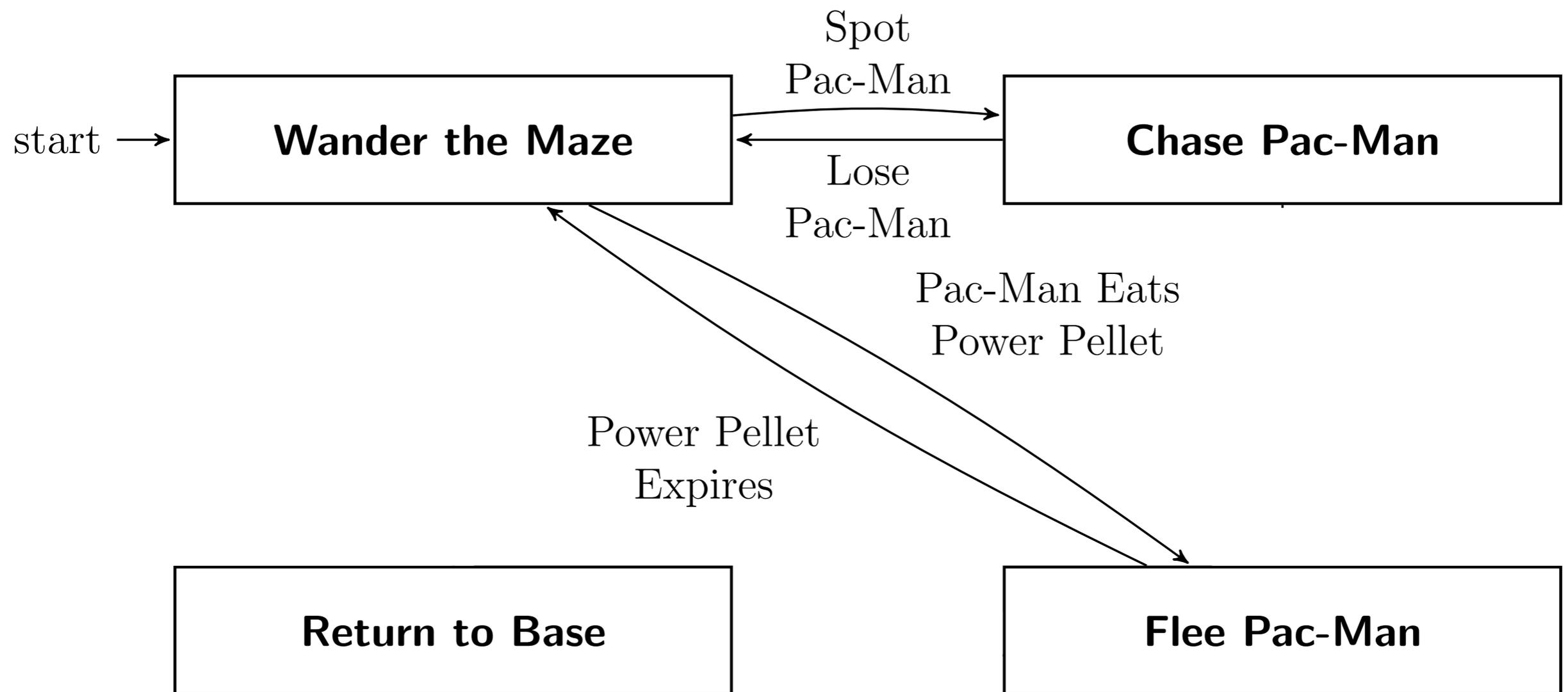
# Example: Pac-Man Ghosts



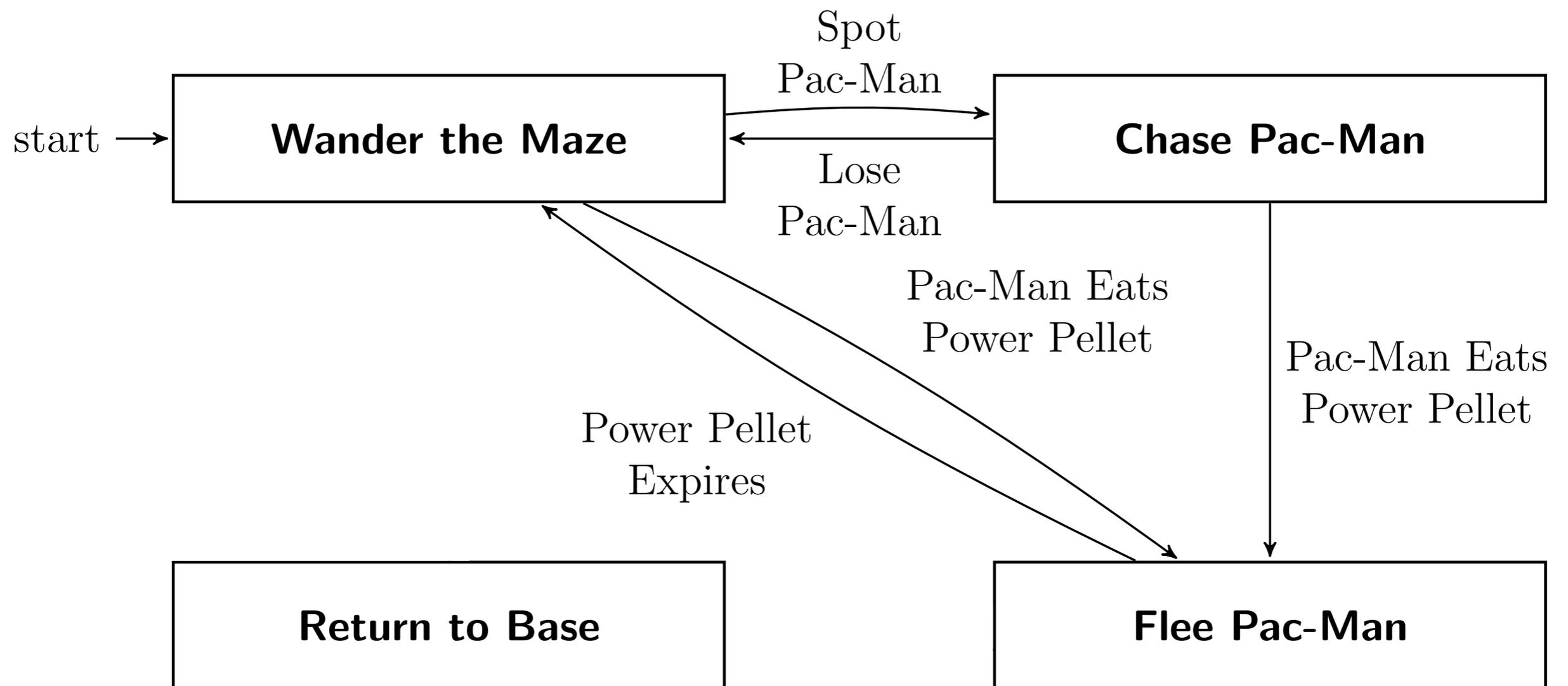
# Example: Pac-Man Ghosts



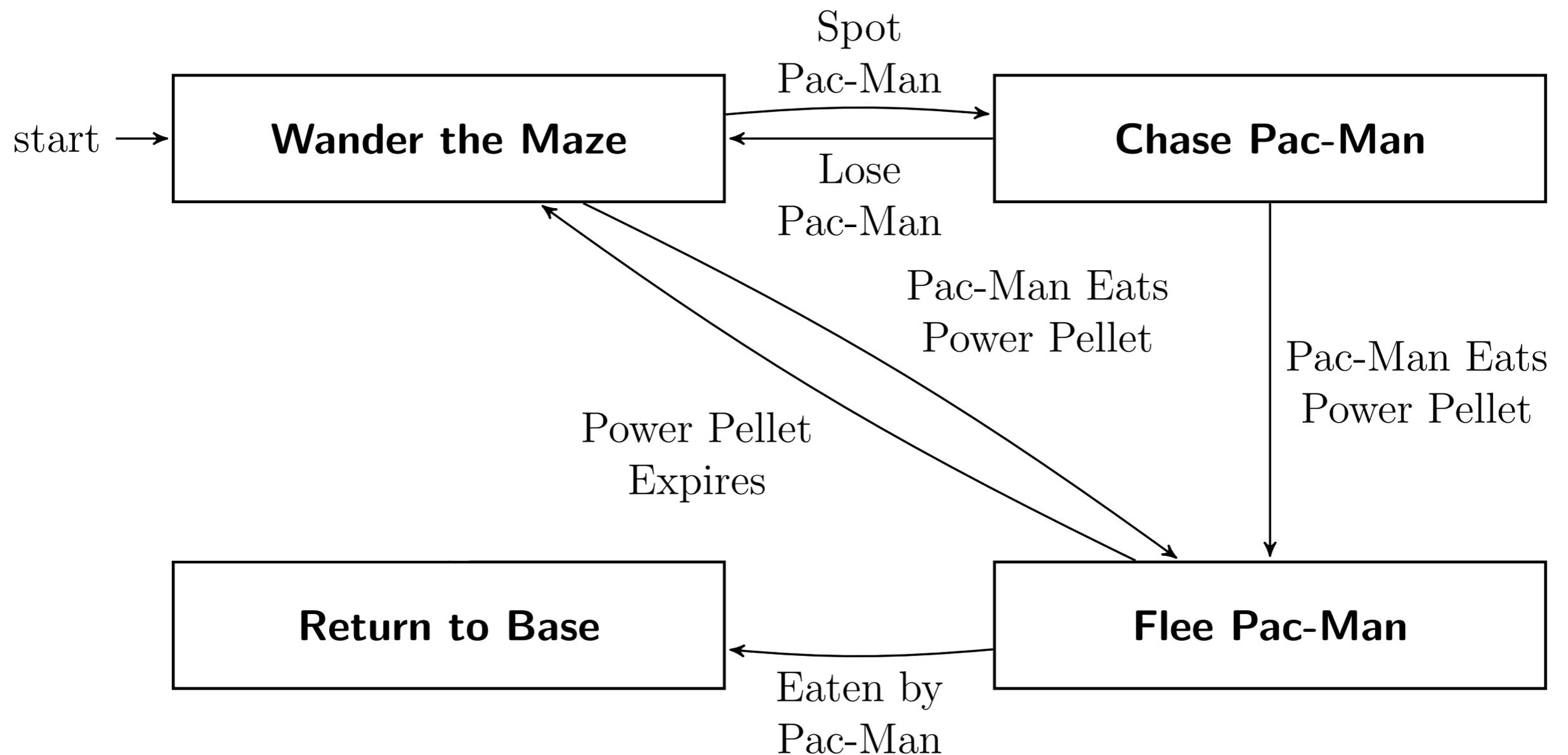
# Example: Pac-Man Ghosts



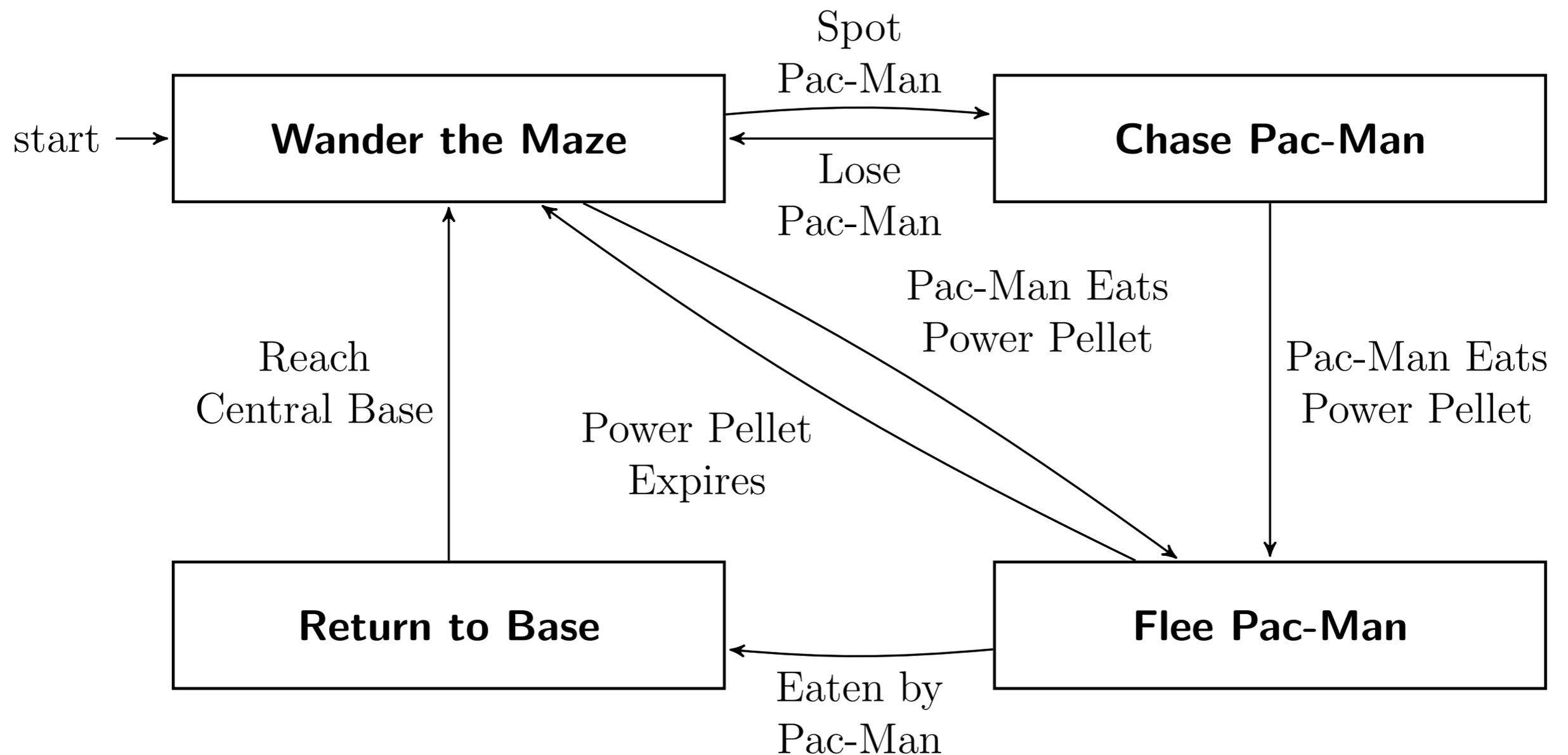
# Example: Pac-Man Ghosts



# Example: Pac-Man Ghosts



# Example: Pac-Man Ghosts



# Exercises

Without adding states, draw the automata for a SuperGhost that can't be eaten. It chases Pac-Man when the power pill is eaten, but returns to base if Pac-Man eats a piece of fruit.

Choose a favourite (video) game, and try drawing the state automata for one of the computer controlled characters in that game.

# From automata to Petri nets

# DFA

A **Deterministic Finite Automaton (DFA)** is a tuple  $A = (Q, \Sigma, \delta, q_0, F)$ , where

- $Q$  is a finite set of states;
- $\Sigma$  is a finite set of input symbols;
- $\delta : Q \times \Sigma \rightarrow Q$  is the transition function;
- $q_0 \in Q$  is the initial state (also called start state);
- $F \subseteq Q$  is the set of final states (also accepting states)

# Kleene-star notation $A^*$

Given a set  $A$  we denote by  $A^*$

the set of finite sequences of elements in  $A$ , i.e.:

$$A^* = \{ a_1 \cdots a_n \mid n \geq 0 \wedge a_1, \dots, a_n \in A \}$$

We denote the empty sequence by  $\epsilon \in A^*$

For example:

$$A = \{ a, b \} \quad A^* = \{ \epsilon, a, b, aa, ab, ba, bb, aaa, aab, \dots \}$$

# Extended transit. func. (destination function)

Given  $A = (Q, \Sigma, \delta, q_0, F)$ , we define  $\hat{\delta} : Q \times \Sigma^* \rightarrow Q$  by induction:

**base case:** For any  $q \in Q$  we let

$$\hat{\delta}(q, \epsilon) = q$$

**inductive case:** For any  $q \in Q, a \in \Sigma, w \in \Sigma^*$  we let

$$\hat{\delta}(q, wa) = \delta(\hat{\delta}(q, w), a)$$

$(\hat{\delta}(q, w))$  returns the state reached from  $q$  by observing  $w$ )

# String processing

Given  $A = (Q, \Sigma, \delta, q_0, F)$  and  $w \in \Sigma^*$  we say that  $A$  **accept**  $w$  iff

$$\hat{\delta}(q_0, w) \in F$$

The **language** of  $A = (Q, \Sigma, \delta, q_0, F)$  is

$$L(A) = \{ w \mid \hat{\delta}(q_0, w) \in F \}$$

# Transition diagram

We represent  $A = (Q, \Sigma, \delta, q_0, F)$  as a graph s.t.

- $Q$  is the set of nodes;
- $\{ q \xrightarrow{a} q' \mid q' = \delta(q, a) \}$  is the set of arcs.

Plus some graphical conventions:

- there is one special arrow  $Start$  with  $\xrightarrow{Start} q_0$
- nodes in  $F$  are marked by double circles;
- nodes in  $Q \setminus F$  are marked by single circles.

# String processing as paths

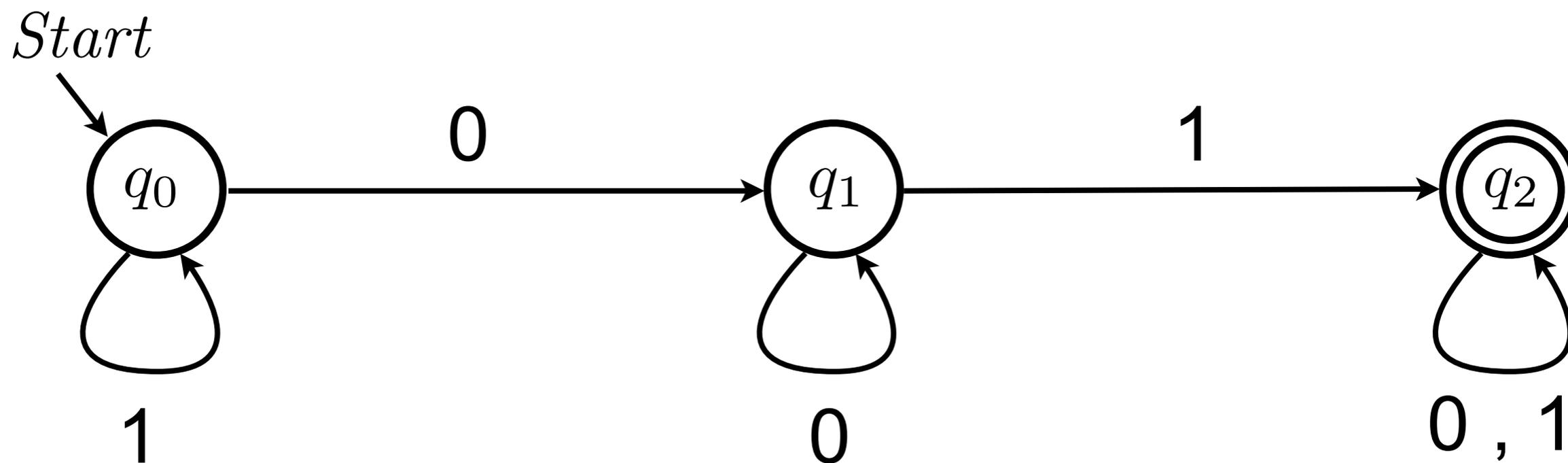
A DFA accepts a string  $w$ , if there is a path in its transition diagram such that:

it starts from the initial state

it ends in one final state

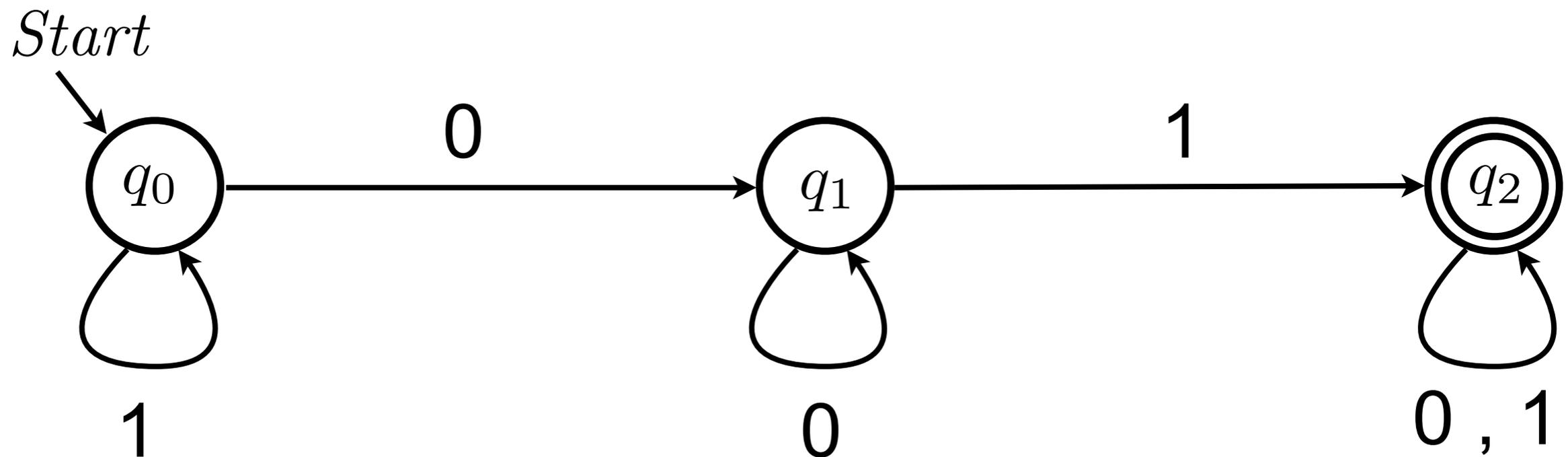
the sequence of labels in the path is exactly  $w$

# DFA: example



$q_0$	1	$q_0$	1	$q_0$	1	$q_0$	0	$q_1$	0	$q_1$	0	$q_1 \notin F$
$q_0$	1	$q_0$	0	$q_1$	0	$q_1$	1	$q_2$	1	$q_2$	0	$q_2 \in F$

# DFA: question time



Does it accept 100 ?

Does it accept 011 ?

Does it accept 1010010 ?

What is  $L(A)$  ?

# Transition table

Conventional tabular representation

its rows are in correspondence with states

its columns are in correspondence with input symbols

its entries are the states reached after the transition

Plus some decoration

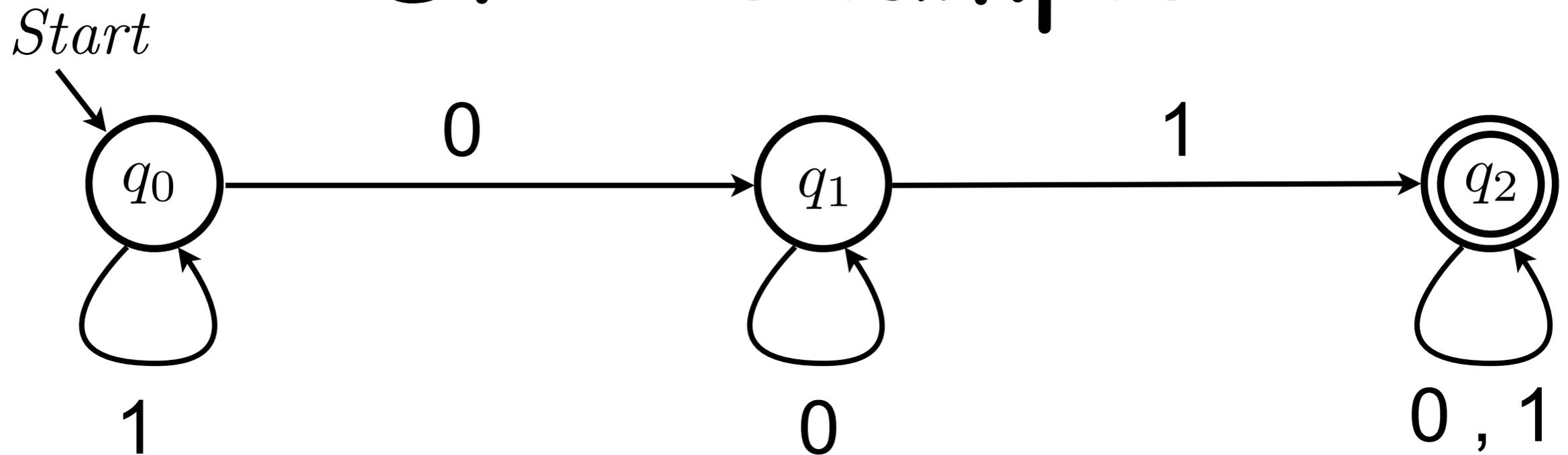
start state decorated with an arrow

all final states decorated with \*

# Transition table

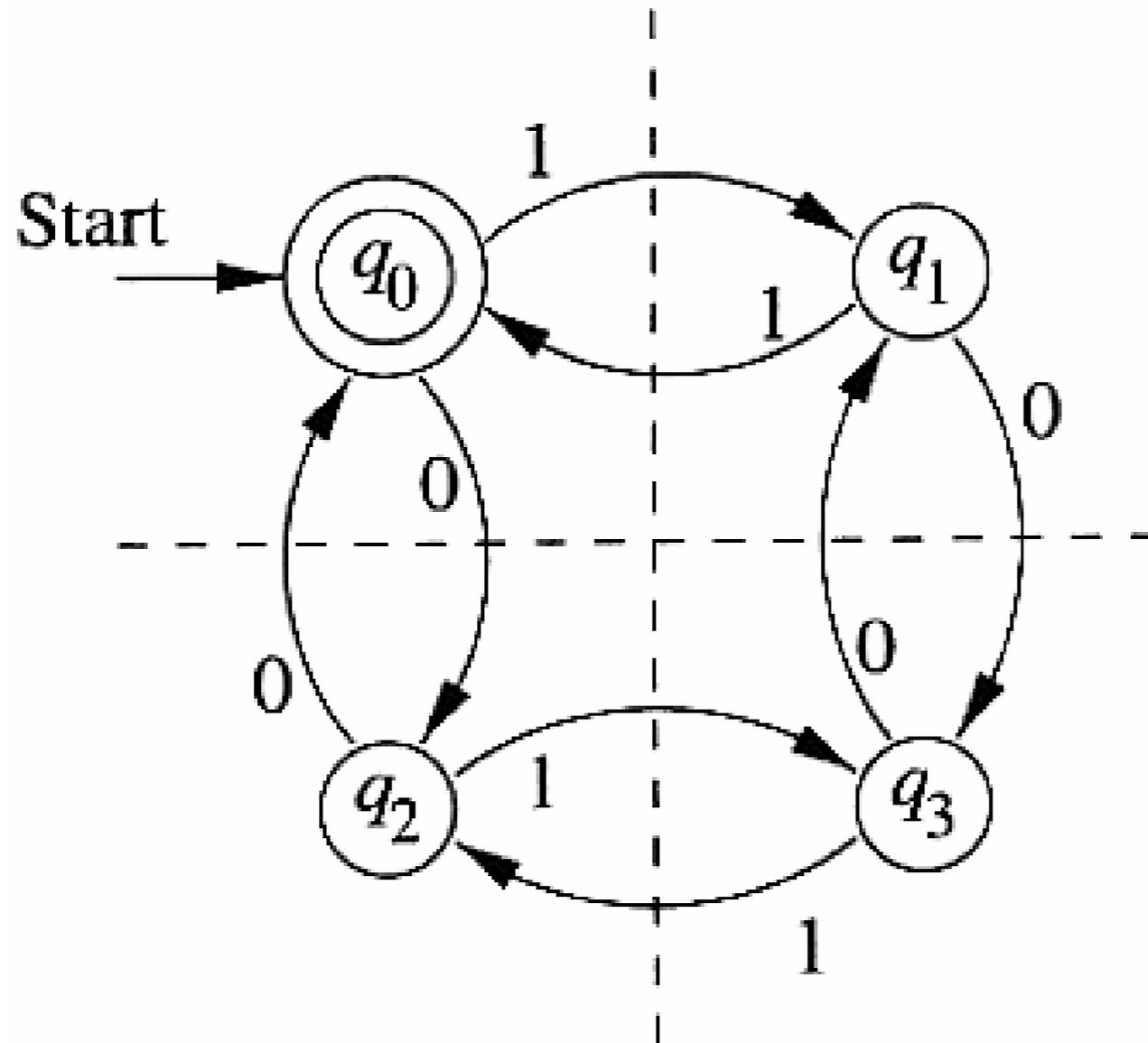
				a			
→							
q				$\delta(q, a)$			
*							
*							

# DFA: example



	0	1
$\rightarrow q_0$		
$q_1$		
$\star q_2$		

# DFA: exercise



Does it accept 100 ?  
Write its transition table.

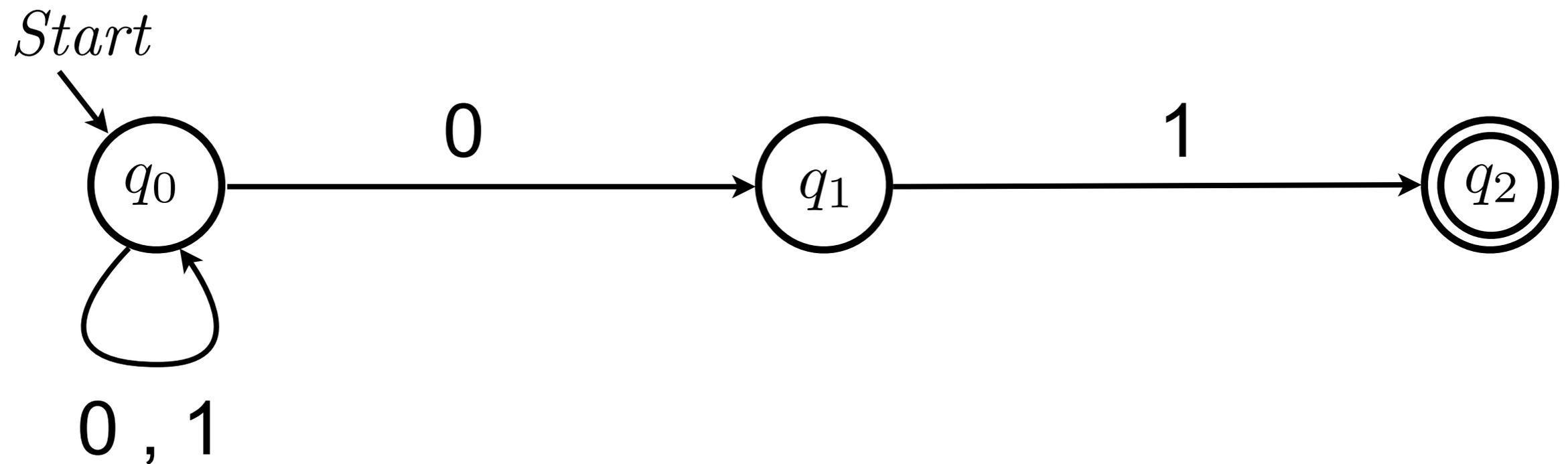
Does it accept 1010 ?  
What is  $L(A)$  ?

# NFA

A **Non-deterministic Finite Automaton (NFA)** is a tuple  $A = (Q, \Sigma, \delta, q_0, F)$ , where

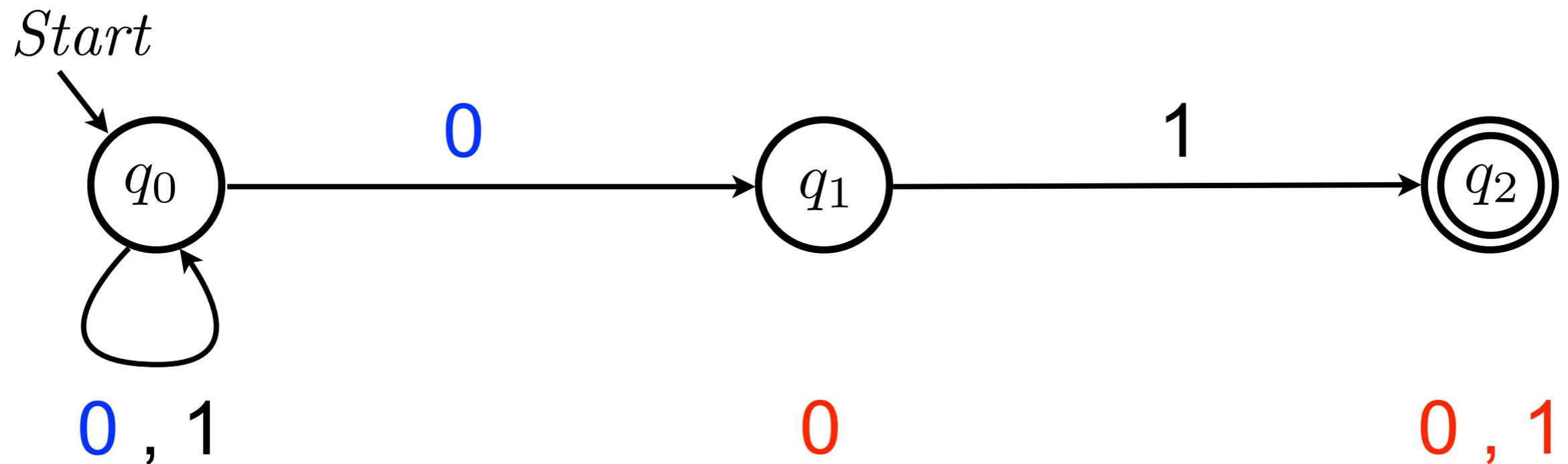
- $Q$  is a finite set of states;
- $\Sigma$  is a finite set of input symbols;
- $\delta : Q \times \Sigma \rightarrow \mathcal{P}(Q)$  is the transition function;   
 powerset of  $Q$  = set of sets over  $Q$
- $q_0 \in Q$  is the initial state (also called start state);
- $F \subseteq Q$  is the set of final states (also accepting states)

# NFA: example



Can you explain why it is not a DFA?

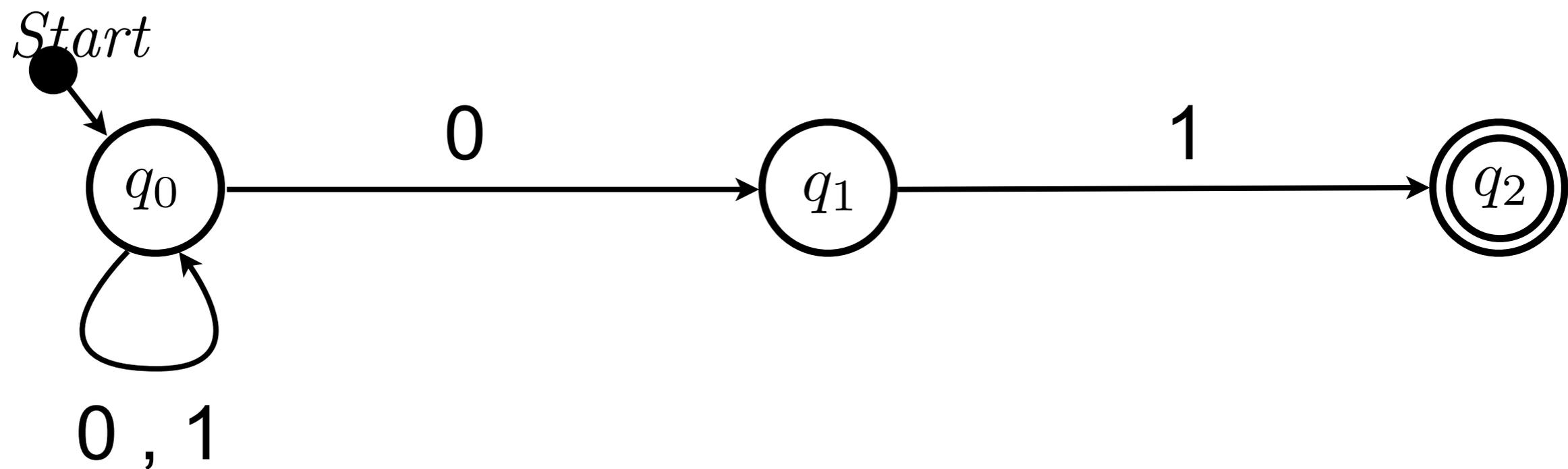
# NFA: example



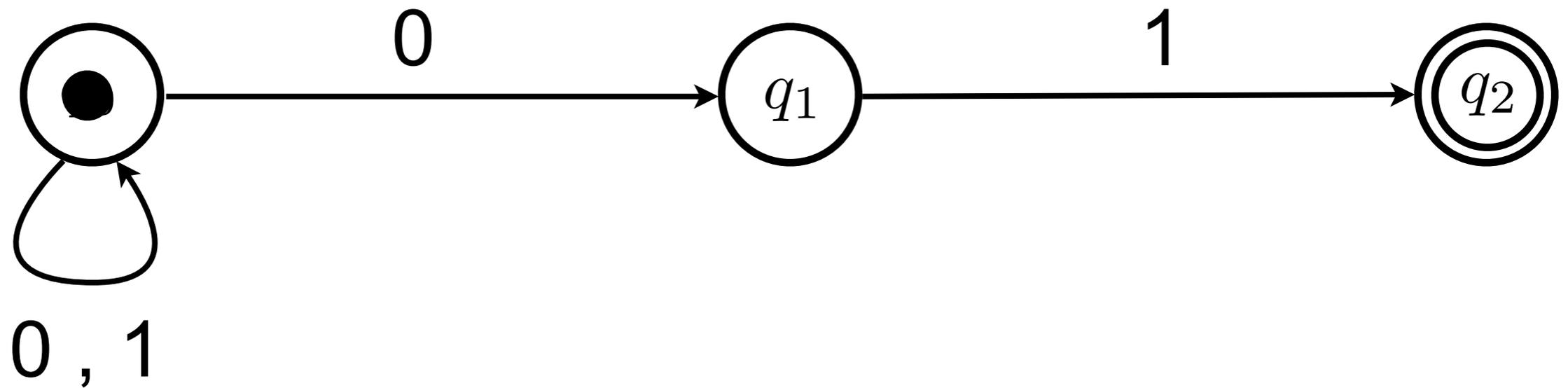
Can you explain why it is not a DFA?

# Reshaping

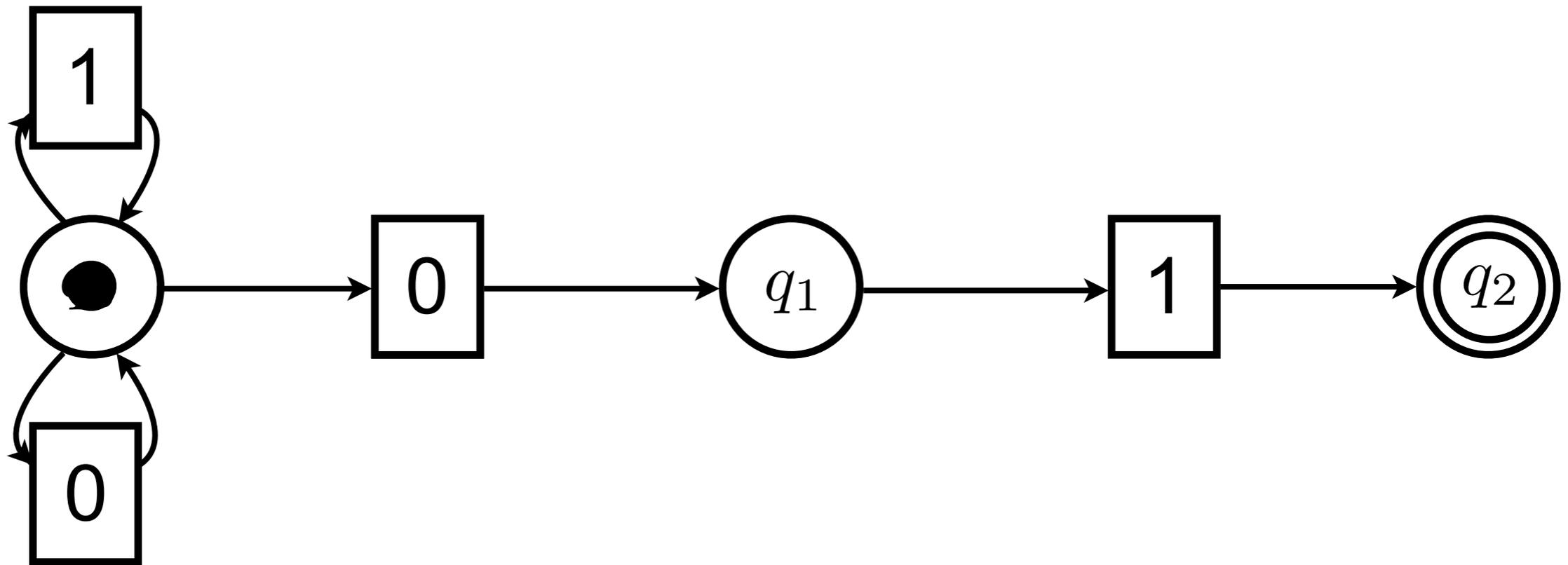
# Step 1: get a token



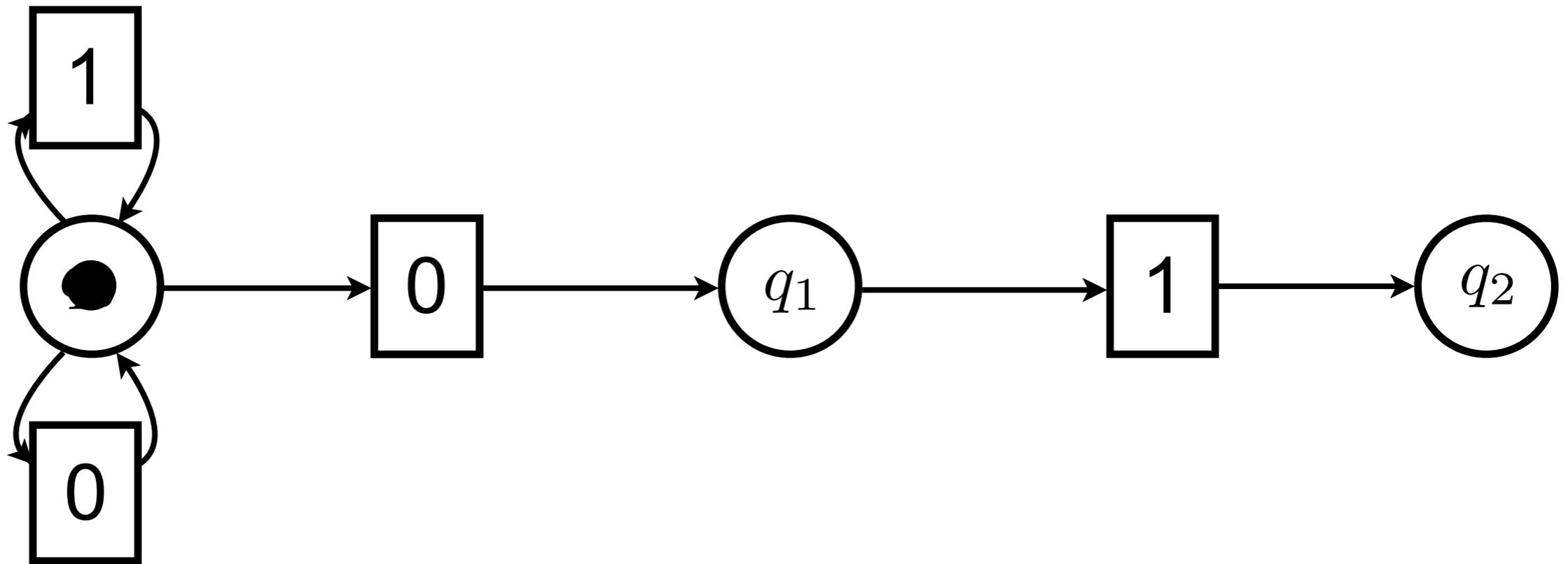
# Step 2: forget initial state decoration



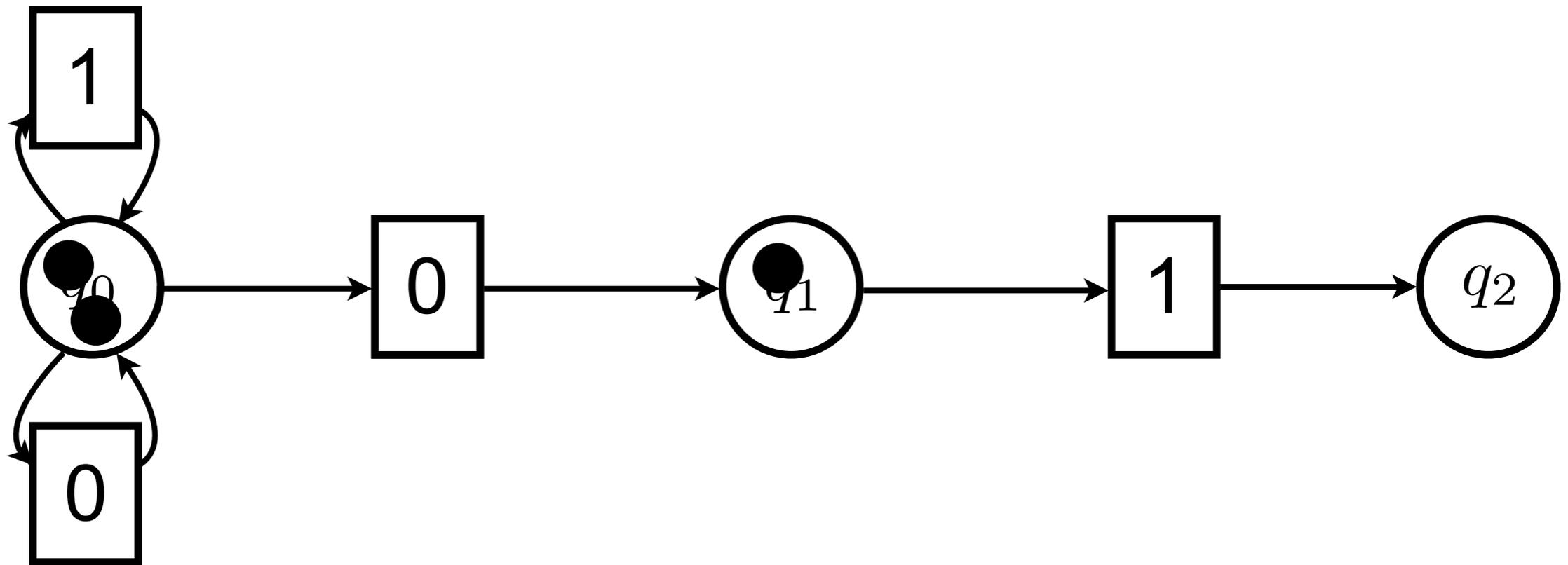
# Step 3: transitions as boxes



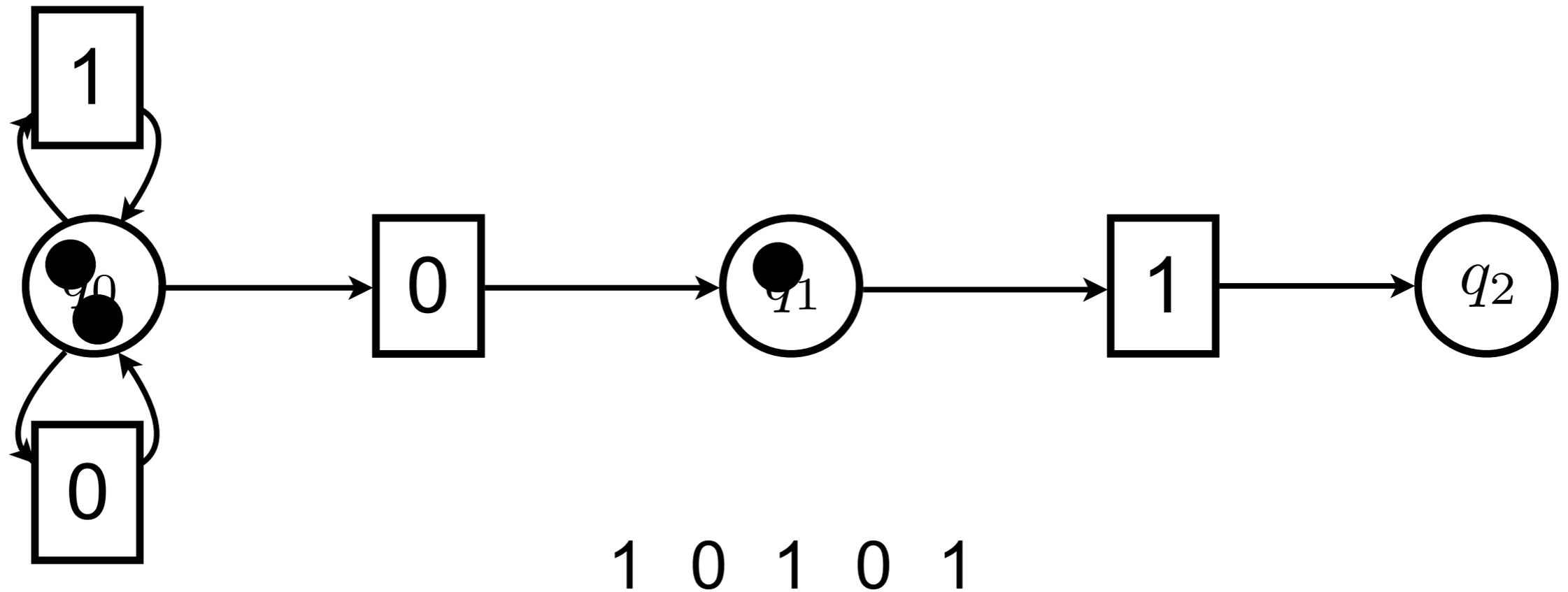
# Step 4: forget final states



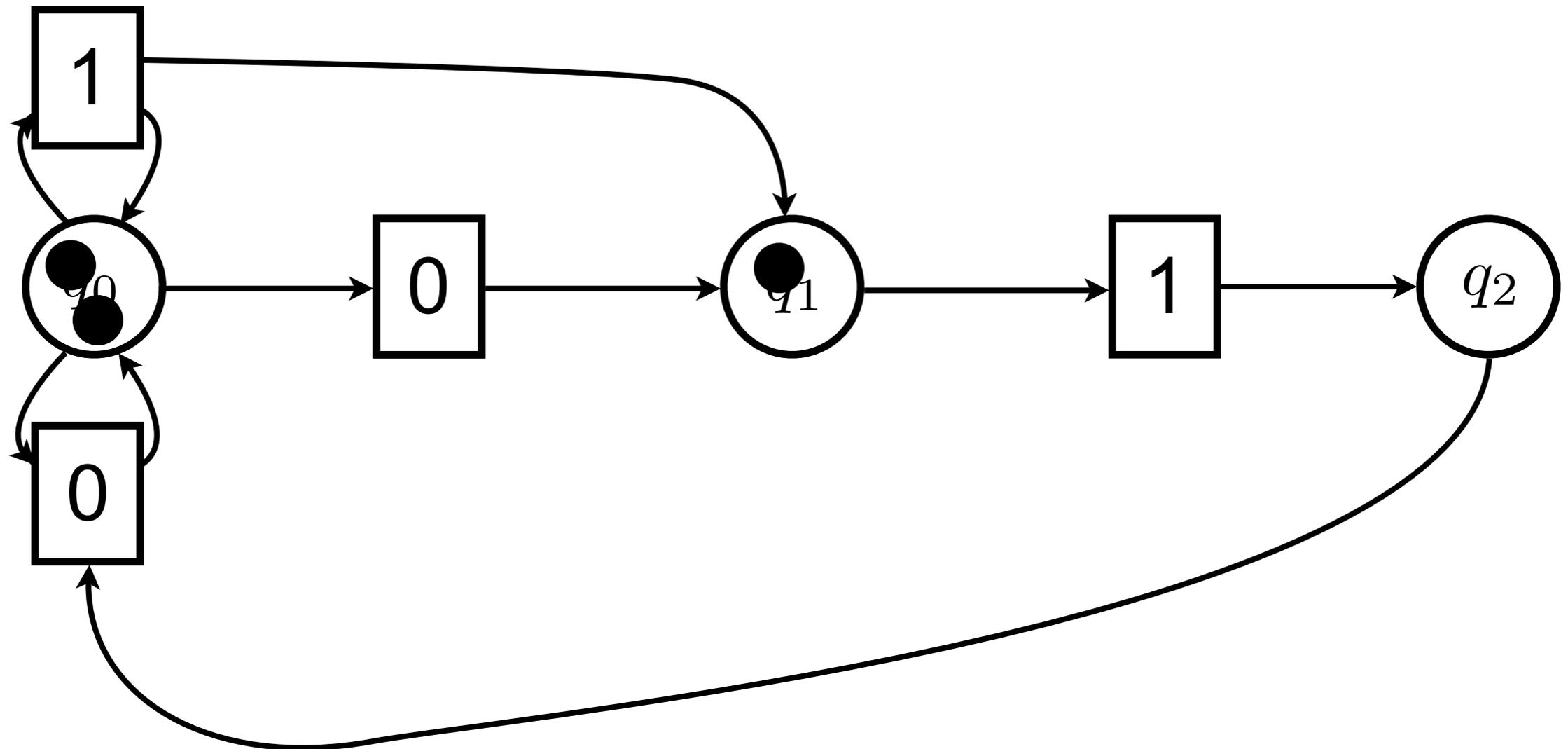
# Step 5: allow for more tokens



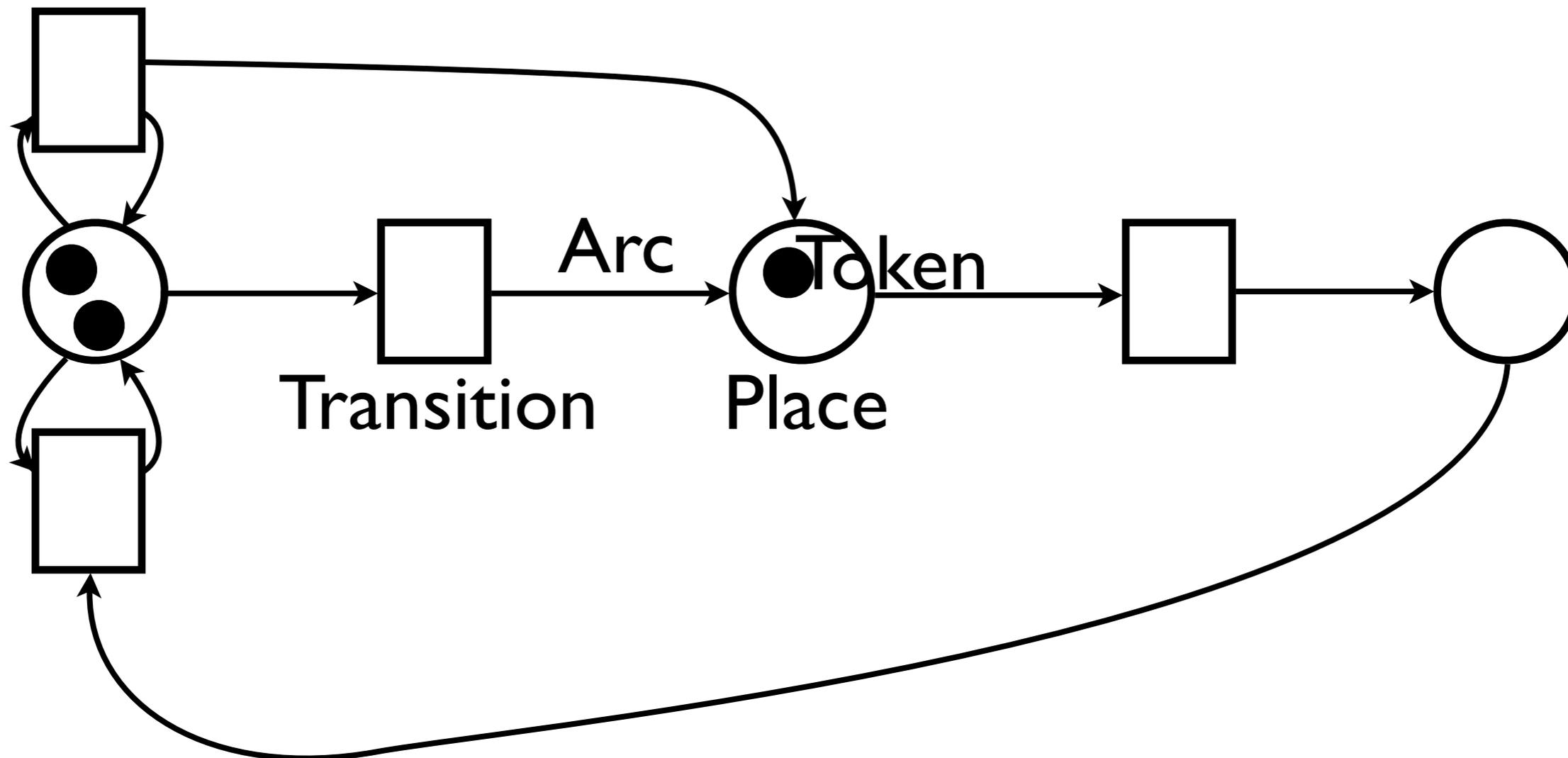
# Example: token game



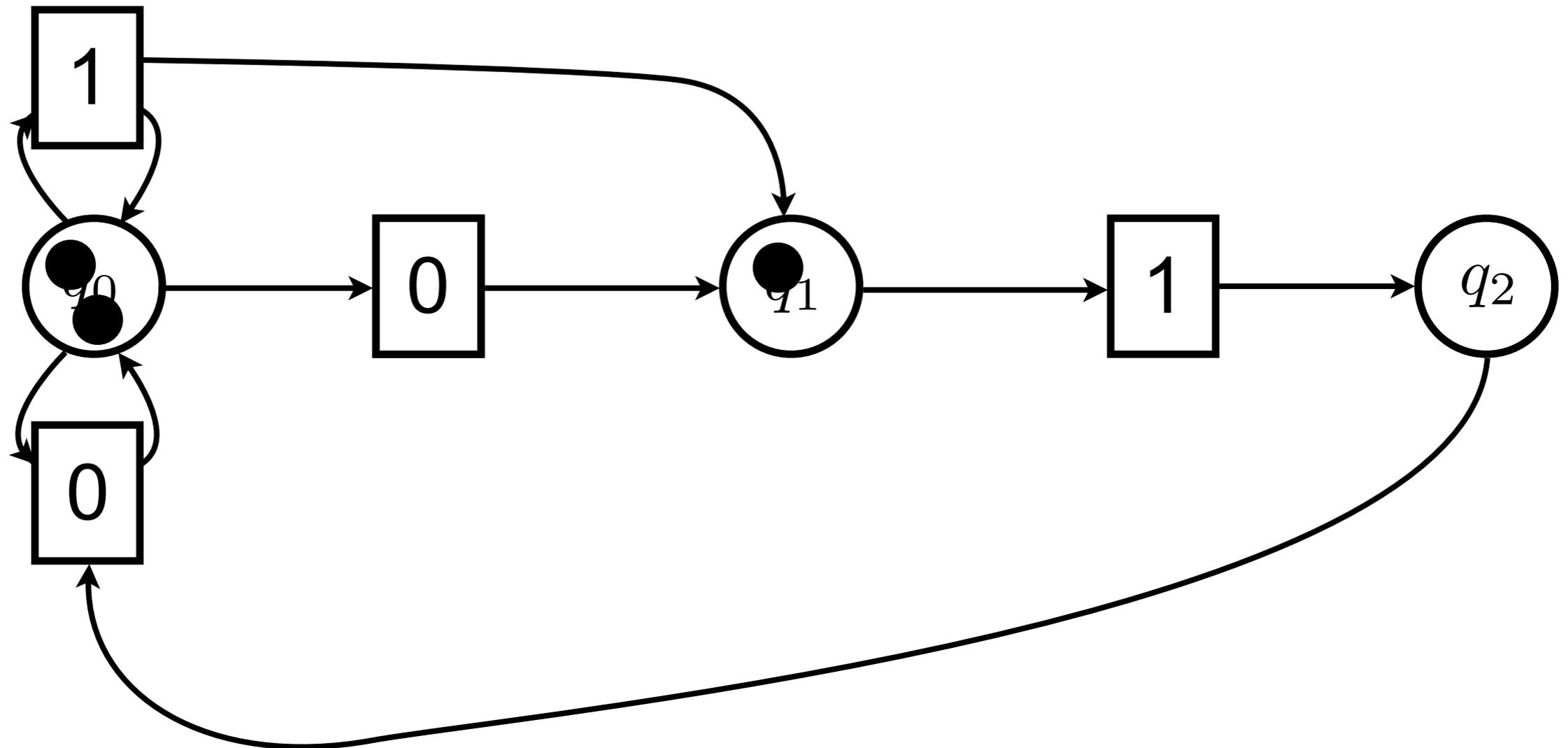
# Step 6: allow for more arcs



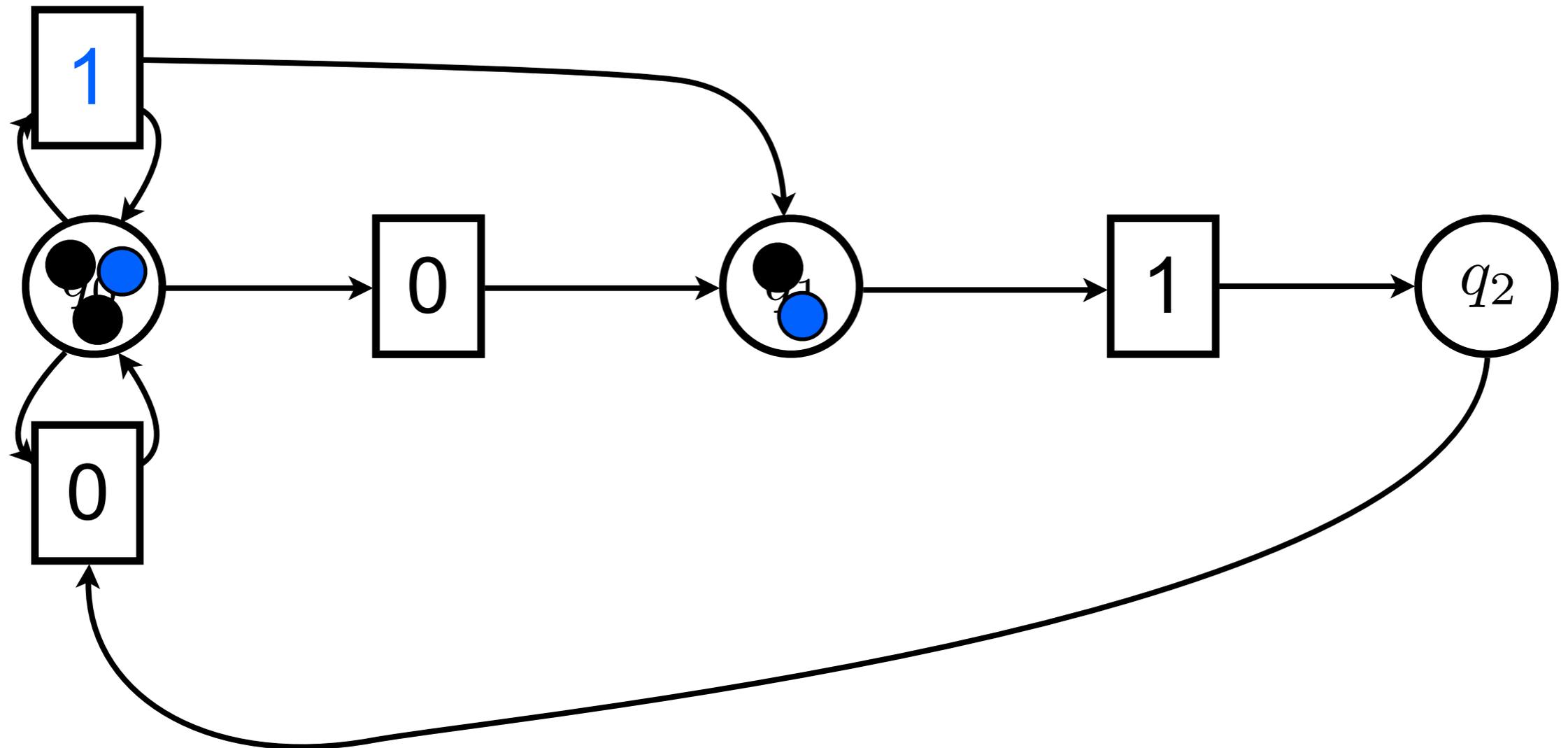
# Terminology



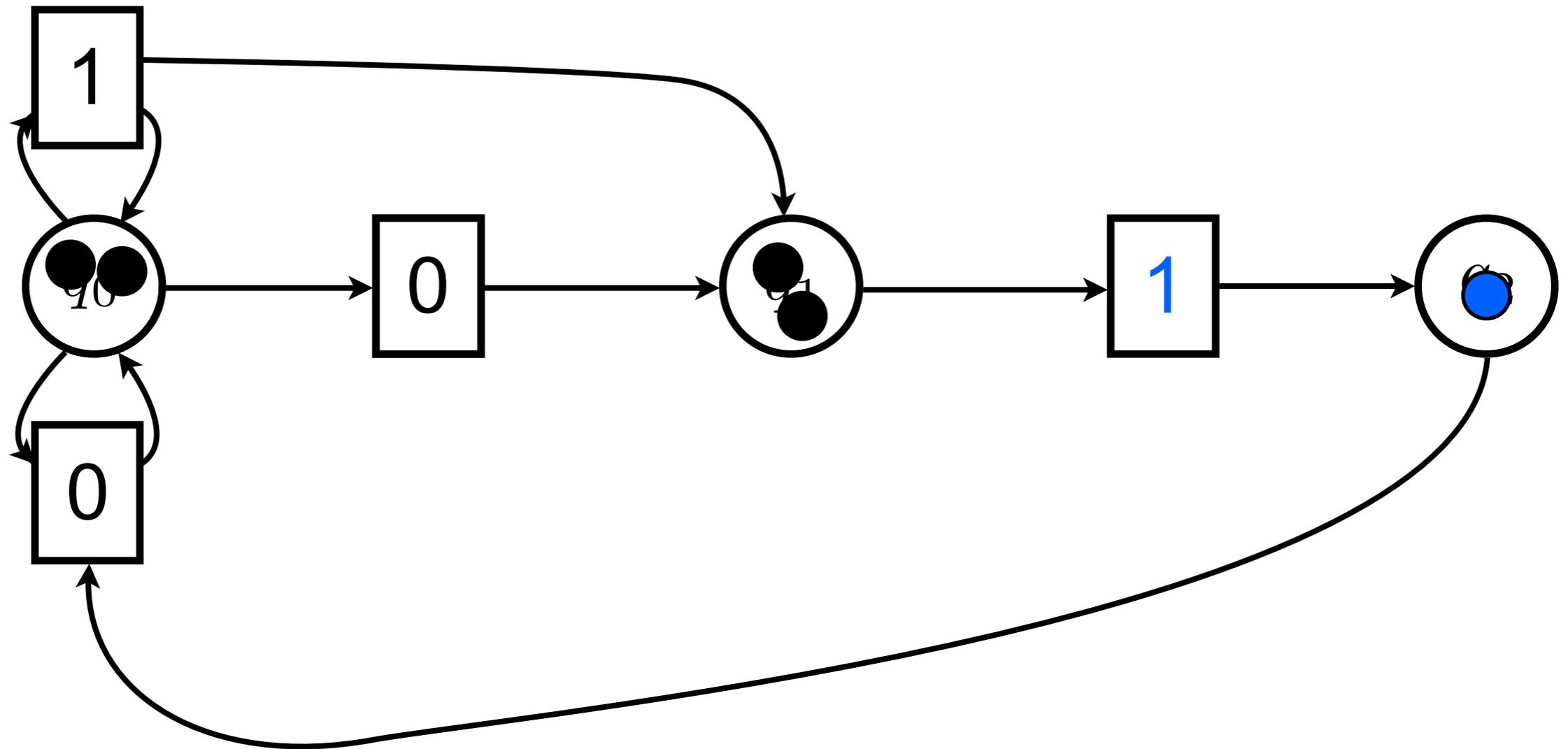
# Example: token game



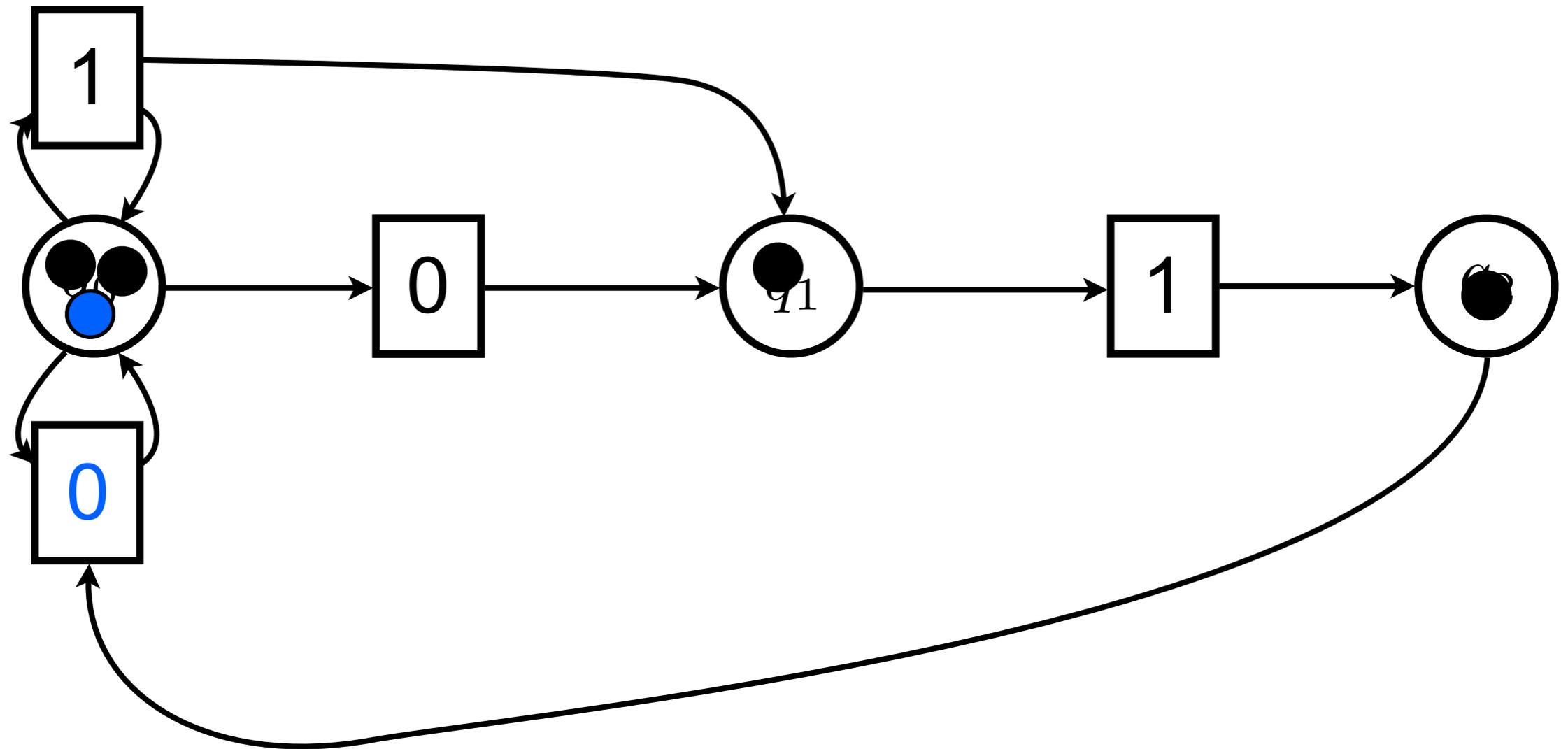
# Example: token game



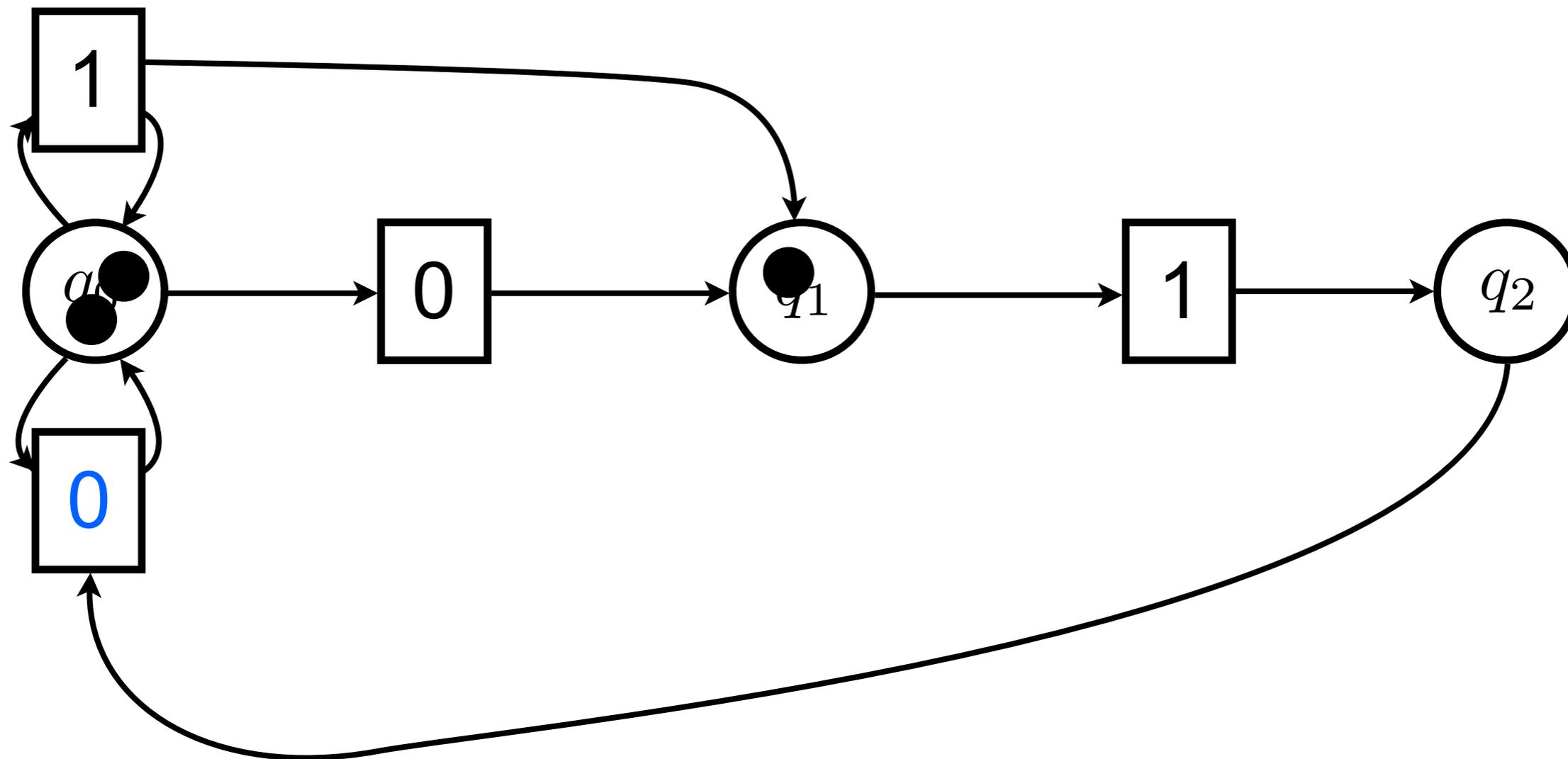
# Example: token game



# Example: token game



# Example: token game



# Some hints

Nets are **bipartite graphs**:  
arcs never connect two places  
arcs never connect two transitions

Static structure for dynamic systems:  
places, transitions, arcs do not change  
tokens move around places

**Places are passive** components  
**Transitions are active** components:  
tokens do not flow!  
(they are removed or freshly created)