

# Statistical Methods for Data Science

Lesson 13 - Unbiased estimators. Efficiency and MSE

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# Statistical model for repeated measurement

- A dataset  $x_1, \dots, x_n$  consists of repeated measurements of a phenomenon we are interested in understanding
  - ▶ E.g., measurement of the speed of light
- We model a dataset as the realization of a random sample

## Random sample

A *random sample* is a collection of i.i.d. random variables  $X_1, \dots, X_n \sim F(\alpha)$ , where  $F()$  is the distribution and  $\alpha$  its parameter(s).

- Challenging questions:
  - ▶ How to determine  $E[X]$ ,  $Var(X)$ , or other functions of  $X$ ?
  - ▶ How to determine  $\alpha$ , assuming to know the form of  $F$ ?
  - ▶ How to determine both  $F$  and  $\alpha$ ?

# An example

**Table 17.1.** Michelson data on the speed of light.

850	740	900	1070	930	850	950	980	980	880
1000	980	930	650	760	810	1000	1000	960	960
960	940	960	940	880	800	850	880	900	840
830	790	810	880	880	830	800	790	760	800
880	880	880	860	720	720	620	860	970	950
880	910	850	870	840	840	850	840	840	840
890	810	810	820	800	770	760	740	750	760
910	920	890	860	880	720	840	850	850	780
890	840	780	810	760	810	790	810	820	850
870	870	810	740	810	940	950	800	810	870

- What is an estimate of the true speed of light?

$$x_1 = 850, \text{ or } \min x_i, \text{ or } \max x_i, \text{ or } \bar{x}_n = 852.4 ?$$

# An example

- Speed of light dataset as realization of

$$X_i = c + \epsilon_i$$

where  $\epsilon_i$  is measurement error with  $E[\epsilon_i] = 0$  and  $\text{Var}(\epsilon_i) = \sigma$

- We are then interested in  $E[X_i] = c$
- How to estimate?
- Use some info. For  $X = X_1$ :

$$E[X] = E[X_1] = c \quad \text{Var}(X) = \text{Var}(X_1) = \sigma$$

- Use all info. For  $\bar{X}_n = (X_1 + \dots + X_n)/n$ :

$$E[\bar{X}_n] = c \quad \text{Var}(\bar{X}_n) = \frac{\text{Var}(X_1)}{n} = \frac{\sigma}{n}$$

Hence, for  $n \rightarrow \infty$ ,  $\text{Var}(\bar{X}_n) \rightarrow 0$

# Estimate

## Estimate

An *estimate*  $t$  is a value that obtained as a function  $h()$  over a dataset  $x_1, \dots, x_n$ :

$$t = h(x_1, \dots, x_n)$$

- $t = \bar{x}_n = 852.4$  is an estimate of the speed of light
- $t = x_1 = 850$  is another estimate
- Since  $x_1, \dots, x_n$  are modelled as realizations of  $X_1, \dots, X_n$ , estimates are realizations of the corresponding sample statistics  $h(X_1, \dots, X_n)$

## Estimator

An estimate  $t = h(x_1, \dots, x_n)$  is a realization of the random variable:

$$T = h(X_1, \dots, X_n)$$

The random variable  $T$  is called an *estimator*.

- $T = \bar{X}_n = (X_1 + \dots, X_n)/n$  is an estimator of the speed of light
- $T = X_1$  is another estimator

# Parameter estimation

- The probability distribution of an estimator  $T$  is called the *sampling distribution* of  $T$
- The standard deviation of the sampling distribution is called the *standard error* (SE)

## Unbiased estimator

An estimator  $T = h(X_1, \dots, X_n)$  of some parameter  $\theta$  is *unbiased* if:

$$E[T] = \theta$$

If the difference  $E[T] - \theta$ , called the *bias* of  $T$ , is non-zero,  $T$  is called a *biased* estimator.

- $E[T] > \theta$  is a positive bias,  $E[T] < \theta$  is a negative bias
- Sometimes,  $T$  is written as  $\hat{\theta}$ , e.g.,  $\hat{\mu}$  denotes an estimator of  $\mu$
- *When is an estimator better than another one?*
- *Is there a best possible estimator?*

# When is an estimator better than another one?

## Efficiency of unbiased estimators

Let  $T_1$  and  $T_2$  be unbiased estimators of the same parameter  $\theta$ . The estimator  $T_2$  is *more efficient* than  $T_1$  if:

$$\text{Var}(T_2) < \text{Var}(T_1)$$

- The *relative efficiency* of  $T_2$  w.r.t.  $T_1$  is  $\text{Var}(T_1)/\text{Var}(T_2)$
- Speed of light example:
  - ▶  $E[X_1] = E[X_2] = \dots = E[\bar{X}_n] = c$ , i.e., all unbiased estimators

The mean is more efficient than a single value

$$\text{Var}(\bar{X}_n) = \sigma/n < \sigma = \text{Var}(X_1) \quad \frac{\text{Var}(X_1)}{\text{Var}(\bar{X}_n)} = n$$

# Unbiased estimators for expectation and variance

UNBIASED ESTIMATORS FOR EXPECTATION AND VARIANCE. Suppose  $X_1, X_2, \dots, X_n$  is a random sample from a distribution with finite expectation  $\mu$  and finite variance  $\sigma^2$ . Then

$$\bar{X}_n = \frac{X_1 + X_2 + \dots + X_n}{n}$$

is an unbiased estimator for  $\mu$  and

$$S_n^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2$$

is an unbiased estimator for  $\sigma^2$ .

- Estimates: sample mean  $\bar{x}_n$  and sample variance  $s_n^2$  (see previous lesson)
- $E[\bar{X}_n] = (E[X_1] + \dots + E[X_n])/n = \mu$  and, by CLT,  $\bar{X}_n \sim N(\mu, \sigma^2/n)$
- Why division by  $n-1$  in  $S_n^2$ ?

[Bessel's correction]



$$E[S_n^2] = \sigma$$

$$(1) E[X_i - \bar{X}_n] = E[X_i] - E[\bar{X}_n] = \mu - \mu = 0$$

$$(2) \text{Var}(X_i - \bar{X}_n) = E[(X_i - \bar{X}_n)^2] - E[X_i - \bar{X}_n]^2 = E[(X_i - \bar{X}_n)^2] \quad [\text{by (1)}]$$

$$(3) X_i - \bar{X}_n = X_i - \frac{1}{n} \sum_{j=1}^n X_j = X_i - \frac{1}{n} X_i - \frac{1}{n} \sum_{j=1, j \neq i}^n X_j = \frac{n-1}{n} X_i - \frac{1}{n} \sum_{j=1, j \neq i}^n X_j$$

(4) From (3):

$$\text{Var}(X_i - \bar{X}_n) = \frac{(n-1)^2}{n^2} \sigma^2 + \frac{1}{n^2} (n-1) \sigma^2 = \frac{n-1}{n} \sigma^2$$

• Therefore:

$$E[S_n^2] = \frac{1}{n-1} \sum_{i=1}^n E[(X_i - \bar{X}_n)^2] = \frac{1}{n-1} \sum_{i=1}^n \text{Var}(X_i - \bar{X}_n) = \frac{1}{n-1} n \frac{n-1}{n} \sigma^2 = \sigma^2$$

• For normal distribution of  $X_i$ 's,  $S_n^2 \sim \text{Gam}(n-1, \sigma^2)$  and  $\text{Var}(S_n^2) = \frac{2\sigma^4}{n-1}$

• In general,  $\text{Var}(S_n^2) \rightarrow 0$  when  $n \rightarrow \infty$

# Degree of freedom

- For the estimator  $V_n^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)^2$ :

$$E[V_n^2] = E\left[\frac{n-1}{n} S_n^2\right] = \frac{n-1}{n} \sigma^2$$

- Hence,  $E[V_n^2] - \sigma^2 = -\sigma^2/n$  [Negative bias]
- $V_n^2$  is *asymptotically unbiased*, i.e.,  $E[V_n^2] \rightarrow \sigma^2$  when  $n \rightarrow \infty$
- Intuition on dividing by  $n - 1$ 
  - ▶  $S_n^2$  uses in its definition  $\bar{X}_n$
  - ▶ Thus, they are not independent
  - ▶  $S_n^2$  can be computed from  $n - 1$  r.v. and the mean  $\bar{X}_n$  (the  $n$ -th r.v. is implied)
- The *degrees of freedom* for an estimate is the number of values minus the number of parameters already estimated
- Assume that  $\mu$  is known. Show that  $\frac{1}{n} \sum_{i=1}^n (X_i - \mu)^2$  is unbiased [Prove it]

# Unbiasedness does not carry over

- $E[S_n^2] = \sigma^2$  implies  $E[S_n] = \sigma$  ?
- Since  $g(x) = x^2$  is convex, by Jensen's inequality:

$$\sigma^2 = E[S_n^2] = E[g(S_n)] > g(E[S_n]) = E[S_n]^2$$

which implies  $E[S_n] < \sigma$

*[Negative bias]*

- In general, if  $T$  unbiased for  $\theta$  does not imply  $g(T)$  unbiased for  $g(\theta)$
- A non-parametric (i.e., distribution free) unbiased estimator of  $\sigma$  **does not exist**

# Estimators for the median and quantiles

- $T = \text{Med}(X_1, \dots, X_n)$ , for  $X_i$  with density function  $f(x)$
- Let  $m$  be the true median, i.e.,  $F(m) = 0.5$ :

[CLT for medians]

$$\text{for } n \rightarrow \infty, T \sim N\left(m, \frac{1}{4nf(m)^2}\right)$$

and then for  $n \rightarrow \infty$ :

$$E[\text{Med}(X_1, \dots, X_n)] = m$$

- $T = \text{Quantile}_p(X_1, \dots, X_n)$ , for  $X_i$  with density function  $f(x)$
- Let  $p$  quantile be the true quantile, i.e.,  $F(q) = p$ :

[CLT for quantiles]

$$\text{for } n \rightarrow \infty, T \sim N\left(q, \frac{p(1-p)}{nf(q)^2}\right)$$

and then for  $n \rightarrow \infty$ :

$$E[\text{Quantile}_p(X_1, \dots, X_n)] = p$$

# Estimator for MAD

- Median of absolute deviations (*MAD*):

$$T = MAD(X_1, \dots, X_n) = \text{Med}(|X_1 - \text{Med}(X_1, \dots, X_n)|, \dots, |X_n - \text{Med}(X_1, \dots, X_n)|)$$

- ▶ For  $X \sim F$ , the population MAD is  $Md = G^{-1}(0.5)$  where  $|X - F^{-1}(0.5)| \sim G$
  - ▶ For  $F$  symmetric,  $Md = F^{-1}(0.75) - F^{-1}(0.5)$ .
  - ▶  $Md$  is a more robust measure of scale than standard deviation
- Under mild assumptions: [CLT for MAD]

$$\text{for } n \rightarrow \infty, T \sim N\left(Md, \frac{\sigma_1^2}{n}\right)$$

where  $\sigma_1$  is defined in terms of  $Md, F^{-1}(0.5), F()$ .

- Then, for  $n \rightarrow \infty$ :

$$E[MAD(X_1, \dots, X_n)] = Md$$

# Estimators for correlation

- Pearson's  $r$  estimator:

$$r = \frac{\sum_{i=1}^n (X_i - \bar{X}) \cdot (Y_i - \bar{Y})}{\sqrt{\sum_{i=1}^n (X_i - \bar{X})^2 \cdot \sum_{i=1}^n (Y_i - \bar{Y})^2}} \quad \rho = \frac{E[(X - \mu_X) \cdot (Y - \mu_Y)]}{\sigma_X \cdot \sigma_Y}$$

- ▶ **Fisher transformation**  $F(r) = \operatorname{arctanh}(r) = \frac{1}{2} \log \frac{1+r}{1-r}$
- ▶ Transform a skewed sample into a normalized format
- ▶ If  $X, Y$  have a bivariate normal distribution:

$$F(r) \sim N(\operatorname{arctanh}(\rho), \frac{1}{n-3})$$

Hence:

$$\tanh(E[F(r)]) = \rho$$

- Same for Spearman's correlation (as it is a special case of Pearson's)

# Estimators for correlation

- Kendall's  $\tau_a$  estimator:

$$\tau_{xy} = \frac{2 \sum_{i < j} \text{sgn}(X_i - X_j) \cdot \text{sgn}(Y_i - Y_j)}{n \cdot (n - 1)} \quad \theta = E[\text{sgn}(X_1 - X_2) \cdot \text{sgn}(Y_1 - Y_2)]$$

- ▶ For  $n > 10$ , the sampling distribution is well approximated as:

$$\tau_{xy} \sim N\left(\theta, \frac{2(2n + 5)}{9n(n - 1)}\right)$$

Hence:

$$E[\tau_{xy}] = \theta$$

**See R script**

# Example: estimating the probability of zero arrivals

- $X_1, \dots, X_n$ , for  $n = 30$ , observations:

$X_i =$  no of arrivals (of a packet, of a call, etc.) in a minute

- $X_i \text{ Pois}(\mu)$ , where  $p(k) = P(X = k) = \frac{\mu^k}{k!} e^{-\mu}$   $[E[X] = \mu]$
- We want to estimate  $p_0 = p(0)$ , probability of zero arrivals
- Frequentist-based estimator  $S$ :

$$S = \frac{|\{i \mid X_i = 0\}|}{n}$$

- ▶ Takes values  $0/30, 1/30, \dots, 30/30$  ... may not exactly be  $p_0$
- ▶  $S = Y/n$  where  $Y = I_{X_1=0} + \dots + I_{X_n=0} \sim \text{Bin}(n, p_0)$
- ▶ Hence,  $E[S] = \frac{1}{n}E[Y] = \frac{n}{n}p_0 = p_0$

*[S is unbiased]*



# Example: estimating the probability of zero arrivals

- Since  $p_0 = p(0) = e^{-\mu}$ , we devise a mean-based estimator  $T$ :

$$T = e^{-\bar{X}_n}$$

- ▶ By Jensen's inequality:

$$E[T] = E[e^{-\bar{X}_n}] > e^{-E[\bar{X}_n]} = e^{-\mu} = p_0$$

Hence  $T$  is biased!

- ▶  $T = e^{-Z/n}$  where  $Z = X_1 + \dots + X_n$  is the sum of  $Poi(\mu)$ 's, hence  $Z \sim Poi(n \cdot \mu)$

$$E[T] = \sum_{k=0}^{\infty} e^{-\frac{k}{n}} \frac{(n\mu)^k}{k!} e^{-n\mu} = e^{-n\mu(1-e^{-1/n})} \rightarrow e^{-\mu} = p_0 \text{ for } n \rightarrow \infty$$

Hence  $T$  is asymptotically unbiased!

[Exercise 19.9]

**See R script**

# Example: estimating the probability of zero arrivals

- Let's look at the variances:

$$\text{Var}(S) = \frac{1}{n^2} \text{Var}(Y) = \frac{np_0(1-p_0)}{n^2} = \frac{p_0(1-p_0)}{n} \rightarrow 0 \text{ for } n \rightarrow \infty$$

$$\text{Var}(T) = E[T^2] - E[T]^2 = \dots \text{ exercise } \dots \rightarrow 0 \text{ for } n \rightarrow \infty$$

**See R script**

# MSE: Mean Squared Error of an estimator

- What if one estimator is unbiased and the other is biased but with a smaller variance?

## MSE

The Mean Squared Error of an estimator  $T$  for a parameter  $\theta$  is defined as:

$$MSE(T) = E[(T - \theta)^2]$$

- An estimator  $T_1$  performs better than  $T_2$  if  $MSE(T_1) < MSE(T_2)$
- Note that:

$$\begin{aligned} MSE(T) &= E[(T - E[T] + E[T] - \theta)^2] = \\ &= E[(T - E[T])^2] + (E[T] - \theta)^2 + 2E[T - E[T]](E[T] - \theta) = Var(T) + (E[T] - \theta)^2 \end{aligned}$$

- $E[T] - \theta$  is called the *bias* of the estimator
- Hence,  $MSE = Var + Bias^2$
- A biased estimator with a small variance may be better than an unbiased one with a large variance!

**See R script**

# Example: number of German tanks



- Tanks' ID drawn at random without replacement from  $1, \dots, N$ . Objective: estimate  $N$ .

# Example: number of German tanks

- Let  $x_1, \dots, x_n$  be the observed ID's
- E.g., 61, 19, 56, 24, 16 with  $n = 5$
- They are realizations of  $X_1, \dots, X_n$  draws with replacement from  $1, \dots, N$ 
  - ▶  $X_1, \dots, X_n$  is not a random sample, as they are not independent!
  - ▶ The marginal distribution is  $X_i \sim U(1, N)$  **[prove it, or see Sect. 9.3]**

- **Estimator based on the mean**

- ▶ we have:

$$E[\bar{X}_n] = E[X_i] = \frac{N+1}{2}$$

- ▶ We can define an estimator

$$T_1 = 2\bar{X}_n - 1$$

- ▶  $T_1$  is unbiased:  $E[T_1] = 2E[\bar{X}_n] - 1 = N$
  - ▶ E.g.,  $t_1 = 2(61 + 19 + 56 + 24 + 16)/5 - 1 = 69.4$

# Example: number of German tanks

- Let  $x_1, \dots, x_n$  be the observed ID's
- E.g., 61, 19, 56, 24, 16 with  $n = 5$
- **Estimator based on the maximum**
  - ▶ Let  $M_n = \max\{X_1, \dots, X_n\}$
  - ▶ We have:

*[see Sect. 20.1]*

$$E[M_n] = n \frac{N + 1}{n + 1}$$

- ▶ We can define an estimator

$$T_2 = \frac{n + 1}{n} M_n - 1$$

- ▶  $T_2$  is unbiased:  $E[T_2] = \frac{n+1}{n} E[M_n] - 1 = N$
- ▶ E.g.,  $t_2 = 6/5 \max\{61, 19, 56, 24, 16\} - 1 = 72.2$

**See R script**